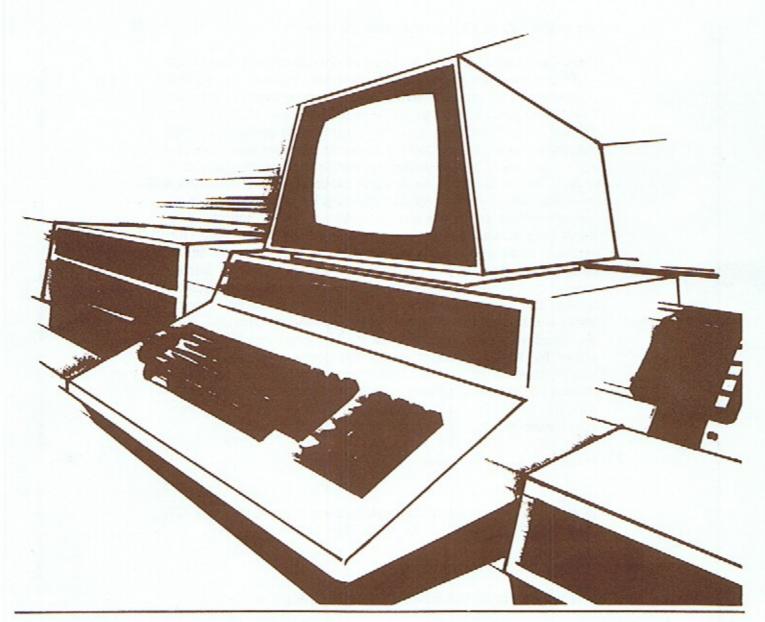
The Official Commodore Pet Users Club Newsletter



Volume 2

Issue 7

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## USER CLUB MANAGER APPOINTED

I am pleased to welcome David Middleton who has joined Commodore as User Club Manager. David is a Mechanical Engineer with extensive BASIC/Machine Code experience. Having run his own PET user group, he has a special interest in assisting local user groups solve the problems of getting off the ground. David has been heavily involved in the editing of this edition of CPUCN and will be taking over the editorship completely as from the first issue of Volume 3.

Whilst it is sad to hand over a job which has brought me a great deal of satisfaction it is rewarding to know that the editorial reins are being handed over to someone who has a keen interest in developing and extending the service offered to User Club members. I will not be leaving CPUCN completely as in the future I will be contributing application stories. I will also be involved with the development of sister publications like MISAC, a copy of which is enclosed. Although MISAC is

# Commodore News

By Andrew Goltz

AFTER THE SHOW

Now that the dust has settled down after the tremendous success of the World's First PET Show, and CPUCN has returned to its usual format, it seems a good idea to review the present position. Several thousand people packed the main ballroom at the Cafe Royal and all exhibitors agreed that their participation had been extremely worthwhile. It seems likely that Commodore will be making the PET Show an annual event, if so then the 1981 event will have to be moved to a more spacious venue! It is unfair to make a selection from the many varied exhibits on the fifty or so stands but special mention should be made of the following: - the BMB Compuscience MUPET system (now being distributed in the UK by Kobra Systems through the Commodore Dealer Network.) - the new Super PET functioning as a remote terminal - and as a wordprocessor running WordPro 4. The position as regards the availability of the 80 column machines is that currently each of the Commodore Commercial Systems Dealers is receiving a single machine for training and familiarisation purposes and dealer's engineers are busy attending special 8000 series engineering courses being run by the Commodore Training Department.

It is expected that the first 8000 series machines will be delivered to users in about 60 days time, which is also the period within which a series of software application packages, currently under development, will be released.

The PET Show User Club seminars also provided a forum in which members could meet Commodore staff, and a number of outside speakers gave first rate presentations. A number of user suggestions are being implemented, and one that readers will immediately notice is the new CPUCN UPDATE section in support of Commodore's Business Software.

intended primarily for use in schools and colleges a copy is being sent to all User Club members as part of our policy of keeping you up to date with all the latest Commodore literature, and I feel that much of the material (especially the Sheridan College article) will be of general interest to users outside the field of education. After you have finished with MISAC why not hand it over to a teacher friend.

One of the most popular speakers at the PET Show seminars was Jim Butterfield, who I would like to personally thank for flying over to the UK at extremely short notice. Jim brought over with him a number of excellent programs which he has put into the public domain. These include CROSS REF and IEEE WATCH which are being reproduced in CPUCN, an improved edition of SUPERMON and a superb version of ADVENTURE which runs on a 32K PET and disk unit! David Middleton will be bringing these programs with him when he visits local user groups and members will be free to make their own copies. Please write to David if your group is interested.

# **Update**

ATTENTION COMPAY & WORDPRO III USERS

Recent batches of PETs have somewhat changed the balance of our video circuitry. The net result is that the fast screen poke has become extremely unreliable to use.

The fast screen poke is designed to speed up the print speed on the PET's screen. There are two versions of it, as follows:

P	oke Location	rast	STOM
1.	59458	60	30
2.	59490	62	30

Version 1. is used in Comwordpro III, and version 2. is used in Compay. In the light of recent hardware developments, both versions must now be classed as OFFICIALLY NOT SUPPORTED.

Compay updates, effective June 1 1980, include removal of the fast screen poke. Comwordpro III is now being shipped without the poke as well. If you have an old version of WP3 and are experiencing difficulties, do the following:

- 1. Load Comwordpro III, DON'T TYPE RUN.
- 2. POKE 5348,234:POKE 5349,234:POKE 5350,234
- 3. Re-save Comwordpro III.

This will remove the fast screen poke from your version of Comwordpro III.

M J R Whitehead

# **Petpacks**

As you will be aware from the advertisement on the back page of our previous newsletter, a company called Audiogenic (tel. Reading [STD CODE 0734] 595269) is handling mail order requests for all Commodore cassette software, and a range of the disk products as well. A growing number of 'add-ons' for the Pet are also available from them, but the main reason for mentioning them is that they are able to distribute copies of our software catalogue, and the new one has just been published. I'd like to draw your attention to this catalogue, as we have announced in it a large number of new cassette titles for the PET. These cover a wide range of applications from word processing to gardening, from utilities to languages, and from entertainment to education.

The last two in particular have seen a great leap in quantity and particularly quality over the last few months, as more and better programs have become available. Our Arcade series of games has produced three wonderfully entertaining and very addictive games, and all three show what can be achieved graphically by the use of machine code. On the education side, there are nine new titles in the current catalogue, and these too show what an increase there has been in the standard of programming since the PET first appeared.

I don't apologise for boasting about these programs - after all, we didn't write them! Our only achievement is in selecting and distributing the best out of a very large number of programs that are written for the PET and to make sure that you don't have any worries when buying a program from Commodore.

But if we don't write them, who does? The answer may well suprise you - you do! If it wasn't for the contributions of people like yourselves, PET devotees, there wouldn't be such a good library of programs for people to enjoy. So, people like Bob Chappell, Deri James, Ted Landsler, Andrew Colin, A. Russell Wills, and the rest, take a pat on the back. And if I didn't mention your name, it's only because space precludes it!

In order to maintain our standards, and to

continue supplying value-for-money software, we obviously need a continuous supply of good programs. This is where you come in. This month I'd like to start a competition, which is, of course, to write a program, and there will be six categories, broken down into two games and four educational programs. These are:

- 1) Simulation of a board game.
- 2) Arcade quality game (like Invaders etc).
- 3) Physics tutorial program.
- 4) Chemistry tutorial program.
- 5) Mathematics tutorial program.
- 6) Biology tutorial program.

Exactly what format these programs can take I'll leave up to you. Suffice it to say that we are looking for a very high quality. The closing date will be two months from the date you receive this newsletter, and the best program in each category will be published in our library of programs, and the winning authors will get a ten per cent royalty on the programs that we sell. If your program is reasonably successful (and a good program usually is!), this could amount to something in the nature of 20 to 30 pounds a week. Can't be bad.

So, budding geniuses, let's see what you can do. Send your entries (on tape please) to :-

Pete Gerrard, Cassette Library Manager, Commodore Business Machines, 818 Leigh Road, Trading Estate, Slough, Berks.

Full details of all the winning programs will be published in 3 newsletters time. Good luck, and I look forward to seeing your programs.

# **Book review**

PET/CBM PERSONAL COMPUTER GUIDE by Carroll S. Donahue and Janice K. Enger

This latest publication from Adam Osborne/McGraw Hill maintains the excellent standards established by their earlier classics such as 'An Introduction to Microcomputers and '6502 Assembly Language Programming •

The book is a well written, comprehensive guide to the PET that will be found useful by the novice, beginning programmer and experienced PET User. The material in the book being well signposted to indicate the level of difficulty.

As expected in Osborne publications diagrams and worked examples are extensively used throughout the book and they successfully compliment the main text. A new departure is the use of photographs and screen displays which help to make the book 'friendly' for the absolute beginner.

Sometimes the book appears to be guilty of providing too much information e.g. the section of PET trivia includes a discussion of what happens when three keys on the PETs keyboard are depressed

simultaneously! But in most instanaces the reader is warned that he is reaching a section which may be skipped at first and often such sections provide invaluable information on PET quirks which provide the experienced PET programmer with useful reference material.

The book includes an introductory chapter that explains the basic concepts common to microcomputers and looks at PET's special features. The next chapter called 'Operating The PET' deals thoroughly with the installation, correct use and maintenance of the PET hardware. The next two chapters deal comprehensively with PET BASIC commands and statements and the techniques of writing, editing and saving programs. Chaper 5, entitled 'Making the most of PET features', discusses string handling, programmed cursor movement, graphics, animation and file handling. PET special features, including the graphics character set, internal clock and Poking screen memory, are well covered. The final chapter

will be especially useful for advanced programmers as it deals with the details of PET's own operating system, and introduces the concept of Machine Code programming.

A comprehensive series of appendices provide memory maps and tables for BASIC 1.0 and BASIC 2.0, and an excellent bibliography completes a well thought out and carefully researched book. I have no hesitation in recommending a copy for every PET user's book-shelf.

The book may be ordered via your local Commodore Dealer or direct by post from Audiogenic Software, P.O. Box 88, Reading, Berks. Tel. 0734 595269.

(Also received 'PET and the GP IEEE/488 BUS' published by Adam Osborne/McGraw Hill which will be reviewed in CPUCN 2.8.)

# Computer philosophy

W.T. Garbutt Mississauga, Ont

"It was the best of times, it was the worst of times, it was the age of wisdom, it was the age of foolishness, it was the epoch of belief, it was the epoch of incredulity, it was the season of Light, it was the winter of despair, we had everything before us, we had nothing before us, we were all going directly to Heaven, we were all going directly the other way—in short, the period was so much like the present period, that some of its noisiest authorities insisted on its being received, for good or for evil, in the superlative degree of comparison only."

So began Charles Dickens in the famous introduction of the 18th Century setting for "A Tale of Two Cities" over a century ago! As with all great literature, the vision Dickens gives is perhaps centuries ahead of its time, in any event just as germane today as it was when Dickens first wrote it. Today Western civilization is on a precipice; the brink of a great leap forward for Humanity or a momentary or perhaps fatal fall.

While less than one-sixth of the world's population consumes over 80% of world resources, hundreds of millions fight daily to survive on the remainder. And those who survive remember!

For the fortunate few, the leap forward has begun. While scholars will argue for generations as to the precise time, (there probably is not one ) the race to the Moon will likely symbolize the start for many. None of the generation of the sixties will forget President Kennedy's proclamation to reach the Moon by the end of that decade ( nor will they likely forget his tragic and senseless death). The last brief decade has witnessed a massive expansion of knowledge, the extent of which is beyond human comprehension. If all knowledge known were increased by the order of a magnitude in the 70's, is there any doubt the increase will be two orders of magnitude this decade? Is there any certainty that this exponential knowledge explosion will quench humankinds' thirst

by the 21st century?

Yes. There is serious doubt if the knowledge does not bring with it a maturity, a compassion for fellow man, a sharing and a sacrifice. The dismal scenario has already been summarized by Mr. Dickens in the 18th century: war, pestilence, famine and destruction. And even with our present limited knowledge is there any doubt that a similar order of a magnitude, an exponential order of horror could soon be our legacy.

There are disquieting signs that the future optimism, our traditional western belief in historical progress may be open to serious question. What Western civilization must guard against is introspection. Cultural isolation will almost certainly provide the impetus for an apocalypse. This introspection can take many forms. Most familiar to the readers of The Transactor is the discipline of electronics and more particularly computers.

Certainly this is a paradox. The computer, the single most important element in the recent knowledge explosion, the genie that could provide the key to the crucial inter-relationships in what at present is an incomprehensible mass of data, surely could not be viewed as retrenchment. On the contrary if a limited number of well educated and affluent people become preoccupied with the computer solely for their own personal intellectual gratification that is precisely what could happen.

However it need not happen. What is required is an atmosphere of freedom, freedom of thought, expression, knowledge freely accessible to all as well as freedom from hunger and poverty. A vast educational challenge exists certainly as great as that witnessed in the race to the Moon. And the micro-computer is ideally suited as a central instrument in meeting the challenge.

One of the major micro-computer

applications will be communications. The micro-computer must become as universally used as the light bulb. It must be available to the 'outbacks' of civilization as well as the present temples of Western civilizations (Universities). Computer literacy must become, with literacy, the prime objective of man after the basic survival improvements over hunger and poverty. No longer must language create communication barriers between nations, no longer may state bureaucracies hide knowledge clandestinely or inadvertently, no longer can corporations shape consumer habits through controlled ignorance.

These freedoms of course carry risks. Change creates instability. Governments and citizens fear unbridled change especially anarchy. But the risks of not accepting the challenge is greater. We could lose all the significant advances that civilization to date has witnessed. The present world population could turn away from a Western tradition that failed to solve humankinds most immediate problems.

The computer can become a central tool to manage today's knowledge, freeing man's creative and underutilized imagination, permitting him time to examine himself.

Today Western civilization senses the future. One has only to witness the long lineups and multi-billion dollar box office receipts for 'science fiction' movies. Today's audiences are seeing implemented

yesterday's dreams. And super realistic depictions of tomorrow. The audiences understand, as never before, the revolutionary technological concepts. Indeed they will accept nothing less. In many instances these special effects were only made possible with the aid of the computer. We must not permit this phenomenon to become a form of escapism. It is important to feed the scientific needs of our citizens. But we must also consider the equally important spiritual needs. eg. beliefs and values.

The computer can provide assistance to man. For every self-gratifying use there is equally a use that will help meet the challenges. From simple energy conservation methods such as controlling house temperature, or arranging car pools to complex techniques to improve work effiency computer uses abound to cut waste.

A recent industry census indicated there are over 500,000 computers in personal use today. Within two years personal ownership is projected to quintuple. Think of the immense number of applications such a user population can generate.

As a member of the micro-computer community, ask yourself the question "What uses can I derive and implement that will aid, no matter how insignificant it may appear, in meeting the challenges of today?" Talk to fellow users, share your ideas and you will likely find yourself in the vanguard of tommorrow's leaders.

## Teach in

SAVING PROGRAMMES UNDER DEVELOPMENT.

When developing and testing programs using disk files there is a significant risk of a hang-up due to simple syntax errors. And if you haven't saved the program, then bang goes a few hours work straight down the drain!

In all my programs I have a standard subroutine called "SAVE PROGRAM UNDER DEVELOPMENT" or "SPUD"! located in lines 60000 to 60999: I write my programs in modules and after completion of each module, before testing, I save the program by executing a direct RUN 60000.

The routine does the following:-

- a. Picks up the program title from a standard position in the first line of the program by peeking the memory. (Because I always lay out my programs in a standard way, I know the first character of the title will always be in the same location.)
- b. Adds the first four digits of the time as held in TI\$ to act as a generation number.
- c. SAVES the program using the combined title and time.

d. VERIFIES the program. The listing is shown at the end of this article.

## 2. SKELETON PROGRAMS

On several occasions, it has been pointed out how useful it is to lay out programs using blocks of line numbers in a standard way. After a while, you find yourself adopting the same line number blocks to perform similar functions whenever they appear in one of your programs. For example, in most of my programs using a menu to display options for the operator to select, the menu display is coded in block 2000-2999 and the selection routine in 2100-2199.

If you find you have adopted some similar convention of your own, why not set up a skeleton program, in order to save a fair amount of typing time at the start of each coding session. In this skeleton program will be the REM statements for the title and preliminary blocks plus the actual coding for all the standard subroutines which are likely to appear in most of your programs.

My own skeleton program runs to 1000

characters which I would have had to type in each time. It contains a Title block, a Preliminaries block and subroutines for Keyboard input, Get a valid character, Cash right align, Delay for 2.5 seconds and Save program under development.

The REM statements at the front of each block, and the underlinings using

minus and equals signs take up a lot of space, but if you have the space spare, I recommend you use them or something similar. It makes listings so much easier to read.

In use, I load "SKELETON", then type in the title of the program being coded into the space reserved for it. From then on, as I finish typing in a module (block) of coding, I save it using SPUD in 60000.

## READY.

```
10 REM TITLE
                 :-"SKELETON
20 REM WRITTEN BY:- M.J. GROSS-NIKLAUS
30 REM FOR
40 REM STARTED ON:-
50 REM LAST AMEND:-
90 GOTO1000
99 ======
100 VARIABLES MAP
101 -----
110 A - Z = GENERAL PURPOSE
111 (I,J,K = G.P. LOOP VARIABLES)
199 ======
200 STRING VARIABLES MAP
201
210 A$ - Z$ = GENERAL PURPOSE
 299 ======
1000 REM PRELIMINARIES
 1001 REM -----
 1099 REM ======
 50000 REM AWAIT VALID KEY
50001 REM--
50010 GETA$:IFA$=""THEN50010
50020 FORZ=1TOLEN(Z$):IFMID$(Z$,Z,1)=A$THENRETURN
 50030 NEXT:GOT050010
50099 REM======
 50100 REM INPUT TRAP
 50101 REM--
 50110 POKE158,3:POKE623,34:POKE624,34:POKE625,20:PRINTZ$;:INPUTA$:A=VAL(A$)
 50120 RETURN
 50199 REM======
 50300 REM 2.5 SECOND DELAY
 50301 REM--
 50310 FORZ=1T02500:NEXT:RETURN
 50399 REM======
 50400 REM CASH RIGHT ALIGN
 50401 REM----
 50410 Z=INT(Z*100+.5)/100
                                "+STR$(Z+.005*SGN(Z)),10),9):RETURN
 50420 Z$=LEFT$(RIGHT$("
 50499 REM======
 60000 REM SPUD
 60010 T$="0:":FORI=1044T01055:IFPEEK(I)=0THEN60030
60020 T$=T$+CHR$(PEEK(I)):NEXTI
 60030 T$=T$+LEFT$(TI$,4)
 60040 PRINT"WSAVING #";T$:SAVET$,8
 60050 VERIFYT$,8
READY.
```

## A USEFUL TIP FOR PROGRAM LISTINGS.

Most printers have a double-line spacing facility yet it seems to be very rarely used for program listings. The improvement in legibility using double line spacing is very worthwhile. Perhaps more important, you can decide on amendments and write them in under or over the lines involved, without being at the PET.

When I started using the PET in early 1978, I did all my coding and development work at the keyboard, in direct contradiction to my main-frame training. Now the old disciplines

have re-established themselves, I use double spaced listings all the time. I separate the sheets and put them into a clip-board, and work on them on train journeys for example. An added bonus is to sprawl outside on the grass on one of those rare sunny midweek afternoons, clip board and pen close at hand, commanding ones colleagues not to disturb you while you debug your program!

On the 3022 Commodore printer, you can open up the lines by a specified amount using a PRINT# to secondary address 6. The version I use is:-

OPEN1,4,6:PRINT#1,CHR\$(45):CLOSE1

## ENGINEERING TRAINING

The Training Department hasn't been the same since the first of May. On that day, Spiro Omfalos joined us from the Service Department. Using techniques which he has obviously adopted from the "Road Runner" films, typing with one hand, operating an oscilloscope with the other, while talking on the phone and listening to a cassette recording, he has put together one of the country's best micro-computer servicing courses in a period of four weeks. How do I know it's so good? Because that is what 90% of those present on the first course said, and backed it with maximum scores on our course appraisal sheets.

Service courses won't affect most of you personally, but it's nice to know that Commodore Dealer engineers have that kind of backup available.

Coming shortly will be conversion courses for the 8000 series equipment. Dealers, please contact Biddy Clark on 01 388 5702 for details.

ASSEMBLER COURSE.

Since we cancelled our assembly language (machine code) course due to lack of support, enquiries regarding such courses have built up. I intend to run a few this year possibly leading to a regular series next year.

The first one will be in late September/early October with Cranfield Institute of Technology as the probable venue for a three day residential course.

My intention is to make this a beginner's course, starting with micro-architecture, binary and hex, and leading to the point where you can confidently use the mini-assembler in EXTRAMON to write useful machine code routines. After attending the course, you should be able to teach yourself the full assembler from the manual.

Projected price is £275.00p inclusive of meals and accommodation but excluding VAT. Ring Biddy Clark on 01 388 5702 for details.



43 Grafton Way, London W1P 5LA Tel: 01-387 7388

## **★ 16-CHANNEL A-D CONVERTOR UNIT**

- 16 inputs, 8-bit resolution
- Input ranges 0-2 5v, 0-5v, 0-10v, single ended (customer specified)
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- BNC front panel connectors
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- LED indicates each relay's state
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## - PRICE: £350

## **★ 8-CHANNEL D-A CONVERTOR**

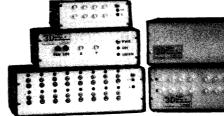
- 8 single-ended outputs, 8-bit resolution
- Output ranges 0.2 5v, 0-5v (customer specified)
- Front panel BNC connectors
- PRICE: £350

## ★ 8-CHANNEL DATA ACQUISITION UNIT

- Interfaces to most digital instruments
- 8 channels of 8 bits each
- Plus two handshake lines/channel
- BCD or byte oriented data
- PRICE: £400

# INTRODUCE YOUR PET TO THE OUTSIDE WORLD

with our range of IEEE-488-compatible interface units. Boxed complete with power supply, leads, switch, fuse, indicators & illustrative BASIC software supplied. Address selectable.





TERMS: All prices ex.VAT. 5% discount for CWO or payment within 14 days of order. Cheques should be made payable to 3D Digital Design & Development. P&P extra. All goods are supplied under 90 days warranty. ALL UNITS EX.STOCK.

CUSTOM DESIGN UNDERTAKEN.

# **COMMODORE TRAINING** DEPARTMENT

# Assembly Language Course

Location:	Cranfield	Institute	of	Technology,
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Bedforshire.

September 23 - 25 1980 Date:

£275.00 + VAT (inclusive of accommoda-Fee:

tion and meals.

To take you to the point where you can Aim:

> write useful machine code routines using the EXTRAMON mini-assembler and dis-

assembler.

Start Point: You should have some familiarity with the

concepts of programing (in BASIC or

some other high level language).

Functioning of a micro-processor Syllabus:

> Main registers in the 6502 processor Holding information in Binary and Hex

Addressing memory The fetch execute cycle The 6502 instruction set

Using the EXTRAMON assembler and dis-

assembler

Binary addition and subtraction

**Boolean operations** Addressing modes

Linking to PET ROM routines

Linking machine code routines into BASIC

programs

The course met my requirements. I'd Coding for the User Port

Hard work but very valuable.

Very friendly. Steady, thorough tutoring. I find it extremely helpful to have tutors who I find it extremely neiprul to have tutors who are both practical and practising the subject matter of the course. Thanks for the course. Your 'User Friendliness' rating is very high. Very good, enjoyable course. Full marks to your awareness of the particpant's requirements.

Course very well organised and well run with a good sense of humour! Many thanks, and you will probably see me again on an advanced course in the future — it was very good value for money.

The course met my requirements. I recommend it to others if the need i am now much more confident of using the disk unit to its full potential.

## **COURSE BOOKING/ENQUIRY COUPON**

I would like to book on/receive further details of the ASSEMBLY LANGUAGE COURSE. September 23 - 25 at Cranfield.

arose.

Name									 			 			 				 	 	 			 		 		 		 		
Address							• •	•	 		•	 			 				 	 	 ٠.			 	 •	 		 		 		
	• • •	<i>.</i>		٠.			•	•	 ٠.	٠.	•	 ٠.	•		 ٠.				 ٠.	 	 		 •	 	 • 1	 	٠.	 	•	 ٠.	٠.	
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I enclose my cheque payable to Commodore Business Machines (UK) Ltd. in the sum of £																																

Please return this slip to: Commodore Training Department 360 Euston Road, London NW1 3BL

# **Beginning BASIC**

## STRING HANDLING IN BASIC LANGUAGE

Most people are aware of a computer's calculating abilities. However, there is another side to computing that is not as familiar to the average person. We have all been exposed to computerised mailing lists, credit information, airline ticket reservations or some other example of the computers data handling capability. The purpose of this article is to relate how some of these things can be accomplished even using a microcomputer such as the Commodore PET.

Most microcomputers today come with BASIC as the major language. BASIC was designed to be a very simple language, easily learned, which can handle most of the operations that are associated with large computers. The penalizing aspect of BASIC is the speed of execution which is often not a major consideration in the use of fixed handling data. We will try to explain each and include examples.

Before we begin the discussion of the commands of BASIC, it is necessary to define some terms. We must understand how the computer stores its data as code numbers. The microcomputer is actually only capable of storing numbers in the range from 0 to 255. As a result of this some standard codes have been created. The code convention used by micros is called ASCII (American Standard for Computer Interchange of Information). For example, in ASCII code the letter "A" is represented by the number 65, "B" by 66, and so forth. The computer contains a decoding routine that automatically decodes the 65 and prints out an "A". Numbers can be represented in three ways inside the computer. The first is as a literal string using the ASCII representation in each number. No arithmetic can be done on numbers represented this way. The most common representation is called "floating point". The computer allocates a number of bytes or memory locations (usually five or six) to represent a number in a way which makes all the arithmetic possible. The last representation is called "Integer" where the range of the number is restricted to +/- 32767 as rounded integers. The only important part is that most micros handle data, either numeric or alphabetic, as the first classification- literal strings of ASCII characters. Since some arithmetic process is usually necessary, there are techniques for converting between the various data representations.

## BASIC AND STRING HANDLING

A "string" is represented in BASIC by a "\$" following the variable name. For example, A\$, IN\$, or X1\$. A string is a series of ASCII coded characters stored together in a sequence in memory ("A\$=ABCDE"). If we looked where the computer had stored A\$, we would see 65,66,67,68,69 in adjacent memory locations. Note that in the example above

the quotation marks indicate to the computer to store the ASCII values of the letters between them and are therefore mandatory.

Strings of ASCII characters can be manipulated by using a series of commands. The first are LEFT\$, RIGHT\$, and MID\$. These commands allow us to view portions of strings and are used extensively in the retrieval and evaluation of data stored in the computer.

LEFT\$
General form A\$=LEFT\$("ABCDE,2")
Print A\$ will result in AB

The string to be manipulated is entered as a literal (as above in quotes) or as a variable (x\$) followed by a comma and a number. The number designates how many characters starting at the left will be extracted from the main string. LEFT\$ does not change and cannot be made to change the original string in any way.

RIGHT\$
General form A\$=RIGHT\$("ABCDE",2)
Print A\$ will result in DE

Obviously, RIGHT\$ accomplishes the identical task as LEFT\$ but the operation is performed on the other side.

MID\$
General form A\$=MID\$("ABCDE,2,2)
Print A\$ will result in BC

In this case, the first number following the string value is a pointer to the first character to be extracted, starting from the first character on the left (character A is the first, B the second, etc.). The next number designates the number of characters to be extracted. Note that MID\$ cannot be used to modify the original string.

A\$=MID\$("ABCDE",2) this form of the MID\$
command allows the user to remove the
leftmost character ie
A\$="CDE"

In addition to the above string handling commands there are another three instructions which allow manipulation or study of strings.

LEN
General form A=LEN("ABCDE")
Print A will result in 5

LEN returns the length of a string and is used extensively in setting up data in files. We will see more of LEN later.

VAL General form A=VAL(124.35) Print A will result in 124.35

VAL is used to convert literal numbers (as ASCII strings) to their "floating point" form so that arithmetic can be performed.

It is used widely for doing calculations on information stored in data files.

#### STRS

General form A\$=STR\$(A):WHERE A=124.35 Print LEN(A\$) will result in 7

STR\$ is the exact reverse of VAL. It is used to return calculated values to ASCII string form for storage in data files. An important note is that STR\$ always leaves a space at the beginning of the string representation of the number for the sign (+ or-). If the number is positive it is preceded by a space or if it is negative by a minus sign.

The last two string handling commands are normally used in advanced programming to reduce storage requirements to the absolute minimum.

#### ASC(A\$)

General form A=ASC("A")
Print A will result in 65.
This command converts a character to its
ASCII code and allows it to be used in
calculations.

#### CHR\$(A)

General form A\$=CHR\$(65)
Print A\$ will result in A
This is the reverse of ASC and uses the computer's coding logic to generate the appropriate character from a given code number.

## STRING HANDLING OPERATORS

The following operators can be used alone and in combination with the above commands and information to allow very powerful decision making programs using string data. The operators are <,>,= and+.

Since strings are represented as numbers in the computer, they can be handled similarly in many respects. The ASCII code of both numbers ("2") and letters ascend with ascending values of alphabetic order. This allows us to compare apparent magnitudes of strings. It is true that the ASCII code of B(66) is greater than (>) A(65) so we can say that B\$>A\$ or A\$<B\$ of A\$<>B\$. All of these test would be true. This allows us to compare ASCII and place it in alphabetical or numerical order using simple comparison operators. The only difference in the use of these operators for numeric or string information is in the use of (+).

The (+) adds literal characters to the right hand end of the string and increases the string length (LEN) accordingly.

For example: A\$="ABC"+"DE"

Print A will result in ABCDE

In this regard, it is totally different from its arithmetic counterpart.

The true power of the commands discussed up to this point can only be realised as they are used in combinations to compare and manipulate data.

#### PRINT USING

Anybody who has used the PET to output numeric data in tables will know how frustrating it can be to get the columns to align. A table with the following format is all too common:

No	Position	Time
0	1210153312	153.11123
10	12.312	16.215
17	.1273	5.12563127
5	150	0

There are quite a few one line routines which will chop a number around so that it will fit a set format, but none that I have seen which will allow true table layout.

I required a routine which would allow me to output a large amount of data into a table that would just fit an 80 column printer. The following program is the result. It works with disk files but it can easily be modified by changing the channel number so that it reads from tape. i.e. change 8 to 1 in line 270 and miss off the rest of the line:-

#### 270 OPEN5,1

Lines 140-630 have to be altered to give the required data. The input routine shown is for an engine test bed running on petrol or methanol.

Lines 150-260 are the program constants some of which are sent to the printer.

Lines 280-360 are the variables that changed each time the engine was run.

Lines 370-450 perform calculations on the input data.

Lines 460-600 send the data to disk.

When modifying the program it is only necessary to ensure the following items:

- The first item to be sent to disk for each data block is 1. Line 460 sends CH to disk: CH=1.
- The last item to be sent before closing the disk file is 99999 as in line 630.
- 3. The title for the output data is held in F\$.
- 4. The data format is held in P\$ using 'I' to denote Integer output and 'F' to denote Floating point. Spaces act as delimiters between numbers.
- 5. Ensure that the number of items sent to disk for each line matches the number of format fields in P\$!

Any number out of range is shown by '##' in the printout.

#### How the Program Works

Take a simple output format string to be:

Each set of data to be output will be stored on disk as a group of 3 preceded by a check digit and the data block will be terminated by 99999. Thus for example there are three sets of data to be output this will be stored as follows:

1 5 2.3716215 3 1 10.1 2021 9 1 69 95.6275 4 99999

740

The first item is read from disk. If it equals 99999 then there is no more data and the program terminates. The number is discarded after the test.

The position pointer CO is set to the start of P\$.

750

The character under the pointer is assigned to V\$. The pointers FB and FA (Float Before, Float After decimal point) are set to 0. In the above example V\$=" ":CO=1.

A space is printed and the program jumps to 990 which will increment CO.

This is repeated until CO-3 V\$='I'.

The string is now searched until a space is encountered or the end of the string is found.

810

FB is set to the number of I's encountered.

1100

A number is read from disk.

1030/1040

The number is turned into an integer NI and NI is turned into a string. If the length of N\$ is greater than the number of characters set aside for it in FB or if N>IEIO an error message is printed and # symbols are sent to the printer.

1060

When a number is converted into a string it will have a preceding space if it is positive and a '-' if negative.

I have written the routine so that this space is removed for positive numbers thus saving space which is important on tightly packed output. Thus the user has to include an extra I or F into P\$ when negative numbers are going to be output.

If the number is negative then the - sign is put into the first position of the format. eg. N=-50

> IIIII - 50

1080

If the number is positive then blanks are added. Thus numbers are always right justified.

The sample printout will now look like:

5 SSS

770

More spaces are encountered and sent to the printer. When the first 'F' is found CO=8.

840

The string is searched. FB is incremented when FA=0.

850

As soon as the decimal point is found then FA is incremented.

<u>860</u>

When FA>O, FA is incremented.

When the next space is found the program branches.

900

A Floating point number can be considered as an integer + a bit left over. Hence the number before the decimal point is sent to the printer using the integer subroutine in 1030. A decimal point is printed. CS is set to 0

910

As soon as a number drops below .01 it is output in exponential format. When this happens it is necessary to convert it back into floating format by adding in some zeros.

920

CS is set equal to the exponent. eg:

1.237 E- 05 N CS

The actual number is made to conform to the floating point remainder by dividing IO ie:

N=0.1237

950

If 0's are now added between the point and the next number it will be made to conform to true Floating point format. ie. 0.00001237.

970

If CS > FA then only 0's will be output. Starting from the decimal point in N numbers are printed. If the numeric output has still not filled the FA field then trailing '0''s will be printed to pad it out.

CO is incremented by the length of the format FB+FA

There are two operations that the program will not perform these being alphanumeric and exponential output which brings me to the competition.

Modify the program so that alphanumeric data can be input and formatted and add a routine which will convert any number into exponential format. Use A in P\$ for alpha and E for exponential. I would suggest that a block of E's be used with a minimum of 8

being necessary to give output. ie:

EEEEEEEEE -1.763E-10

Set up the program so that it uses cassette

Input/Output and will format to the screen (OPEN1,3) send your modified program to me, Dave Middleton, enclosing a SAE for return of your cassette. The closing date is 1.10.80 and the prize is any program from the Master Library.

```
10 REM*****NOTE - ALL REM STATEMENTS
11 REM*****************************
20 REM*********************
95 REM*******F$ IS TITLE STRING*****
96 REM********* IS FORMAT STRING*****
                                             AFR Y.VOL · TQ
100 F$="RUN SP N LOAD
                            PΗ
                                  MA
                                      MF
                                                                 BP
                                                                       YB SFC"
110 F$=F$+" BMEP"
120 P$=" II II F.F FF.FF FF.FF
130 P$=P$+"FF FFF.FF"
132 REM
135 REM******INPUT MAIN VARIABLES*****
140 OPEN10,4
150 INPUT"DATE";DA$:PRINT#10,"DATE
                                           ":DA$
160 INPUT"JET SIZE"; JE$: PRINT#10, "JET SIZE "; JE$
170 INPUT"NEEDLE, TYPE"; NT$: PRINT#10, "NEEDLE TYPE "; NT$
180 IFTY$="M"THENPRINT#10,"FUEL TYPE: METHANOL"
190 IFTY$="P"THENPRINT#10,"FUEL TYPE: PETROL"
200 CH=1:INPUT"ATOMSPHERIC PRESSURE";PA
210 PRINT#10,"ATMOSPHERIC PRESSURE";PA
220 INPUT"FUEL TYPE IMSETHENOL OR IPSETROL";TY4:IFTY4="M"THENCY=30000:FD=700
230 PRINT#10,"FUEL TYPE: ";:IFTY$="P"THENPRINT#10,"PETROL"
240 IFTY$="P"THENCY=43900:FD=753
250 IFTY≸="M"THENPRINT#10,"METHENOL"
260 PRINT"CALORIFIC VALUE";CV:PRINT"FUEL DENSITY
                                                     ";FD :CLOSE10
264 REM
265 REM*************************
270 OPEN5,8,9,"@1:STEF,S,W"
280 INPUT"RUN NUMBER
290 INPUT"PISTON HEIGHT MM";PH
300 INPUT"SPEED 1000RPM ";N
310 INPUT"LOAD
                    LBS
320 INPUT"DELTA H MMH20
                          ";H
                      *0
330 INPUT"TEMP
340 INPUT"VOLUME
                      ML
350 INPUT"FUEL TIME SEC
                         ";TS
360 INPUT"SPARK TIME "BTC ";SP
364 REM
365 REM*****PERFORM CALCULATIONS*****
370 MA=4*SQR((H*PA)/(T+273))
380 MF=(FD*V)/TS/1000
390 AF=MA/MF
400 YV=51.78*(SQR((H*(T+273))/PA))/N
410 TQ=1.446*L
420 BP=0.1514*L*N
430 YB=(BP*100000)/(MF*CV)
440 SF=8.2/YB
450 BM=9.116*L
454 REM
455 REM******PRINT DATA TO DISK*****
460 PRINT#5,CH:PRINT#5,C0:PRINT#5,SP:PRINT#5,N:PRINT#5,L:PRINT#5,PH:PRINT#5,MA
470 PRINT#5,MF:PRINT#5,AF:PRINT#5,YV:PRINT#5,TQ:PRINT#5,BP:PRINT#5,YB
590 PRINT#5,SF:PRINT#5,BM
595 REM
610 INPUT"ANY MORE DATADDAYUUN";AN$
620 IFAN$<>"N"GOTO280
630 PRINT#5,99999:CLOSE5
644 REM
645 REM******START OF PRINT USING*****
650 OPEN10,4:OPEN4,8,3,"1:STEF,S,R"
654 REM
655 REM*******PRINT TITLES*********
660 FORA=1T080:PRINT#10,"*";:NEXT:PRINT#10
670 PRINT#10,F$
680 FORA=1T080:PRINT#10,"*";:NEXT:PRINT#10
693 REM
695 REM******TEST FOR END IE 99999*****
740 CO=1:GOSUB1100:IFN=99999GOT01010
```

```
744 REM
745 REM***START OF NEXT FORMAT FIELD**
746 REM*****TREAT SPACE AS AN END*****
750 V$=MID$(P$,CO,1):FB=0:FA=0
760 IFV$=""GOTO990
770 IFV$=" "THENPRINT#10," ";:GOT0990
780 IFV$<>"I"GOTO830
784 REM
790 FORC1=COTOLEN(P$):IFMID$(P$,C1,1)=" "GOTO810
800 NEXTC1:FB=LEN(P$)-C0+1:G0T0820
810 FB=C1-CO
820 GOSUB1100:GOSUB1030:CO=CO+FB-1:GOTO990
823 REM
825 REM*****FLOATING POINT ROUTINE****
830 IFV$<>"F"GOTO63999
840 FORC1=COTOLEN(P$):D$=MID$(P$,C1,1):IFD$="F"ANDFA=0THENFB=FB+1
850 IFD$="."THENFA=1
860 IFD$="F"ANDFA>0THENFA=FA+1
870 IFD$=" "GOTO900
880 NEXTC1:IFFA>0THENFA=FA-1
900 GOSUB1100:GOSUB1030:PRINT#10,".";:CS=0:S=N
910 IFABS(N)>1E-2G0T0940
920 CS=INT(VAL(RIGHT$(STR$(N),2))):N=VAL(LEFT$(STR$(N),LEN(STR$(N))-2))/10
930 IFCS>0THENCS=CS-1
940 IFCS=>FATHENCS=FA-1
 950 PRINT#10,LEFT$("000000000",CS);
960 V=2:IFABS(N)<1THENV=1
 970 PRINT#10,MID$(STR$(N)+"00000000",LEN(STR$(INT(N)))+V,FA-CS-1);
 980 CO=CO+FB+FA-1
 985 REM
986 REM****FINISH FORMAT ON THIS****
987 REM******NUMBER. INCREMENT CO*****
 990 CO=CO+1:IFCO=>LEN(P$)THENPRINT#10:GOTO740
 1000 GOTO750
 1005 FORA=1T080:PRINT#10,"*";:NEXT:PRINT#10
 1010 PRINT#10:CLOSE10:CLOSE2
 1020 STOP
 1027 REM
 1028 REM***TURN NUMBER INTO AN INTEGER
 1029 REM*PRINT ERROR IF GREATER THAN FB
 1030 NI=INT(N):N$=STR$(NI):IFLEN(N$)<FB+2ANDNI<1E9G0T01060
 1040 PRINT"ERROR NUMBER OUT OF RANGE"; N: N$=LEFT$("##########",FB):GOTO1090
 1060 N$=RIGHT$(N$,LEN(N$)-1)
                                    ",FB-LEN(N$))+N$:GOTO1090
 1070 IFSGN(N)=-1THENN$=LEFT$("-
 1080 N$=LEFT$("
                      ",FB-LEN(N$))+N$
 1090 PRINT#10,N$;:RETURN
 1097 REM
 1098 REM***READ A NUMERIC STRING FROM
 1099 REMDISK CHOP OF CHR$(10) AT START*
 1100 INPUT#4, CH$: CH$=MID$(CH$,2,200): N=VAL(CH$): PRINTN
                                                       RETURN
READY.
           30 JULY 1980
JET SIZE
            1.001
NEEDLE TYPE 1510
ATMOSPHERIC PRESSURE 761
FUEL TYPE: METHENOL
RUN SP
                                                    BP
        N LOAD
                  PH
                        MA
                              MF
                                   AFR Y. VOL
                                               TΩ
                                                          YB SFC
                                                                     BMEP
1 0 1.0 25.00 25.00 51.10 70.00 0.73 263.4 36.15 3.78
2 0 2.0 29.00 29.00 36.83 22.55 1.63 101.2 41.93 8.78
3 5 3.0 60.00 50.00 41.82 14.00 2.98 82.5 86.76 27.25
                                                          0.18 #.4953 227.9
                                                          1.29 6.3188 264.3
                                                          6.48 1.2637 546.9
```



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If you've three or more PETS, then you need a Mu-pet to make the most of them.

# Programming

## The Use of WAIT

The command WAIT can most usefully be used to test to see if a particular bit is set in a byte.

Implementing the command:-

The keyboard is buffered allowing up to 10 characters to be stored prior to processing. The number of keystrokes to be processed is stored in location 158 (525 Old ROM).

WAIT 158,1 will cause the current program to stop until a key is pressed. What happens is that current value of location 158 will be ANDed bit by bit with 00000001 until a match is made in one bit, then processing continues. This WAIT 158,1 will have the same effect as 10 GETA\$:IFA\$=""GOTO10.

To explain further here are two examples:

- 1. WAIT 158,8 (bit pattern 00001000).

  Each time a key is pressed location
  158 will be incremented. No bit in
  158 will match 00001000 until the
  key has been pressed eight times.
- 2. WAIT 158,7 (bit pattern 00000111)
  Will a key have to be pressed seven times before the programs continues?
  No. The first key pressed will have a bit pattern of 00000001 and this will make a bit match. Hence the program will continue.

A second argument may be added to the WAIT. e.g. WAIT59410,4,4 This will WAIT until the space key has been pressed. If you take a PEEK at 59410 you will find that it contains 255 until a key on the same line as the STOP key is pressed

(RVS 1 space < . =). The space key causes 251 (bit pattern 11111011) to appear in 59410.

It is not possible to use WAIT as any number other than 4 (0000100) will cause the WAIT to be fulfilled and 4 will cause the processor to wait indefinitely.

The first argument performs AND with location 59410.

AND 251 11111011 4 00000100 00000000

This result is then Exclusively ORed (EOR) with the second argument.

An Exclusive OR is the same as OR (01 OR 10 = 11) except that 1 only appears in the result when there is a 0 in the location and a 1 in the argument for the bit.

An Exclusive OR has the opposite effect to OR in that a bit is only set in the result when there is a zero in the location and a corresponding 1 in the argument. e.g.:

EOR 00001111 EOR 00001111 EOR 111110000 111111111 EOR 00001111 EOR 000000000

OR normally has this effect 10101010
OR 01010101
111111111

Going back to the result from WAIT 59410,4,4

251 11111011 AND 4 00000100 00000000 EOR 4 00000100 00000100

And the program will continue.

## CHANGING ARRAY NAMES

Mike Gross-Niklaus

1. The problem.

Over the months, in CPUCN and other publications, many useful subroutines have been listed and explained. Some of these operate on the elements of an array.

But what if you want to use the same subroutine for several arrays? Most of us set up the subroutine with a 'working array', copy the contents of the array to be processed to the working array, perform the subroutine and then copy the processed working array back to the original one. Take a look at diagram 1 to see what I'm getting at.

The trouble is that if the array is a long one, this transferring can take a noticeable time. An alternative approach is to find the reference to the particular array in the array table, change the name to that of the 'working array', perform the subroutine, then change the name back again.

2. Steps involved in changing the name.

First define the old and new names and convert them into the same form as held in the array table.

Then hunt through the table for the old name.

Finally change the name by poking the new code.

To change the array name back again involves the same process, reversing the order of the defined old and new names.

3. Defining the names.

The technique shown here will only work on arrays of the same type (ie real, integer

or string array.) So, assuming that you know what type of array the subroutine is going to process, only the alpha numeric parts of the array name need be specified. For example, whether you want to change XX\$() to WK\$() or XX() to WK(), the procedure will be the same.

The method used requires you to set up in a parameter string (A\$), the old and new names as two characters each, using a space if the name is one character only. For example, to change XX\$ to Z\$ requires A\$="XX,Z".

This parameter string is then passed to a subroutine, 40900, which dissects it to produce the codes for each of the two bytes used by the BASIC interpreter for array names. The rules for these are set out in appendix A of the User Manual. Briefly, the ASCII codes of the alpha-numeric characters of the array name are used, with zero in the second byte if the name has only one character. To these values are added 128 in the second byte if the array is not a real number (floating point) array, and 128 to the first byte if it is an integer array. In the example shown, real arrays are assumed, so the only processing of the ASCII codes required is to replace CHR\$(32), (space) by a zero.

## 4. Hunting for the coded name.

The interpreter maintains some useful pointers in the 'scratch pad' (zero page) section of memory which you can get at with your BASIC programs by using PEEK.

Relevent here are the pointers for the start and end of arrays. The start is held as two bytes in locations 44 (126 old ROM) and 45 (127), and the end in locations 46 (128) and 47 (129). To convert these references into decimal, the second byte is multiplied by 256 and added to the first byte. For example if the first byte contains a PEEKed value of 4 and the second a value of 9, the decimal location is 9 times 256 plus 4 = 2308.

Using these calculations, you can determine the start and end of the search area.

The arrays are laid out with the first two btes as the coded name and the third and forth defining how many bytes to the next array name. So the technique is to check the name pointed at by locations 44 and 45, then if there is no match, add the value of the next two bytes to the pointer and so on, until you find a match or you reach the end of the array area. This skipping search technique is exactly that employed by the interpreter every time it comes across a reference to an array element in your BASIC program, i.e. it searches from the start of the array table each time.

[Incidentally, the same technique is used by the interpreter for looking up normal variables and even line numbers during GOTOs and GOSUBS. Program operation speeds can be significantly improved by putting your most used variables, arrays and subroutines 'at the front of the queue!!']

### 5. Example program.

The example program shows the use of a Bubble sort subroutine on two real number arrays XX and YY. Only 20 elements have been considered to allow listing of the unsorted and sorted arrays on the screen without scrolling or the need for screen page techniques.

The program fills the two arrays with random integer values in the range 1 to 99, and displays them for you to peruse. (I.e "Nothing up my sleeve!!"). After you press the space bar, each array in turn has it's name changed to Z, the bubble sort is done on array Z, then the name is changed back again. Finally the sorted arrays are displayed with the oportunity for another run in case you can't believe your eyes!

Incidently I lay out most of my programs in the manner shown if there is sufficient space. (qv this month's TEACHIN column.)

#### 6. Conclusions.

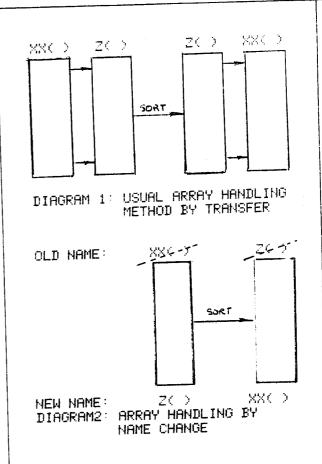
You may feel that it's a lot of work for a not very big reward! Well that depends on the size of your arrays and how frequently you process them during the run of the program. As with all subroutines, once they are written and proven, they are available for instant use whenever you feel the need. In the case of one program I wrote to control industrial equipment, the increase in speed was essential. Using the normal transfer techniques would have caused the system to fail. The program was in PROM so I couldn't POKE the array name change into the BASIC text, which is messy anyhow if you are likely to amend the program with consequent changes in the relevent POKE locations. I could have reverted to machine code, but this method was far easier to implement, and fast enough.

I hope you get some mileage out of the idea, either by using it as intended, or just as an encouragement to you to have a look around the Scratch Pad locations and see what you can do by PEEKing and POKEing.

Mike Gross-Niklaus

```
10 REM TITLE:- ARRAY NAME CHANGE
           :- MIKE GROSS NIKLAUS
20 REM BY
30 REM FOR :- CPCUN
40 REM DATE :- 02/07/80
99 REM =======
100 REM DEMONSTRATION ONLY
999 REM ======
1000 REM PRELIMINARIES
1001 REM -----
1010 DIM XX(20), YY(20): REM TWO ARRAYS
1020 A=RND (-TI): REM RANDOMISE
1030 PT=0: EA=0
1099 REM =======
1100 REM FILL ARRAYS WITH RNDM NOS
1101 REM -----
1110 DEF FNR (X)=INT (RND (1)*X+1)
1120 \text{ FOR I} = 1 \text{ TO } 20
 1130 XX(I)=FNR(99): YY(I)=FNR(99)
 1140 NEXT I
 1199 REM =======
 1200 REM CONFIRM ORIGINAL SEQUENCE
 1201 REM -----
 1210 GOSUB41000
 1220 PRINT"XXPRESS SPACE BAR TO CONTINUE"
 1230 Z$=" ":GOSUB50000
 1299 REM =======
 2000 REM SORT ARRAY XX
 2001 REM -----
 2010 A$="XX,Z ": GOSUB40000: IF EF = 1 THEN END
 2020 T$="XX": GOSUB50800
 2030 A$="Z ,XX": GOSUB40000
 2099 REM =======
 3000 REM SORT ARRAY YY
 3001 REM -----
 3010 A$="YY,Z ": GOSUB40000: IF EF = 1 THEN END
 3020 T$="YY": GOSUB50800
 3030 A$="Z ,YY": GOSUB40000
 3099 REM =======
 4000 REM CONFIRM SORTED ARRAYS
  4001 REM -----
  4010 GOSUB 41000
  4099 REM =======
  5000 REM AGAIN?
  5001 REM -----
  5010 PRINT"XXAGAIN (Y OR N)?
```

5020 Z\$="YN":GOSUB50000:IF I=1 THEN RUN



```
5030 END
5099 REM ======
40000 REM CODE OLD ARRAY NAME
40001 REM -----
40010 X$=LEFT$ (A$,2): GOSUB 40900
40099 REM ======
40100 REM FIND OLD ARRAY NAME
40101 REM -----
40110 EF=0:REM ERROR FLAG RESET
40120 PT=PEEK(44)+PEEK(45)*256
40130 EA=PEEK(46)+PEEK(47)*256
40140 IF PEEK (PT) ONC(1) THEN 40160
40150 IF PEEK (PT+1)= NC(2) THEN 40200
40160 PT=PT+PEEK(PT+2)+PEEK(PT+3)*256
40170 IF PTKEA THEN 40140
40180 EF=1: REM ERROR FLAG
40190 RETURN
40199 REM =======
40200 REM CHANGE THE NAME
40201 REM -----
40210 X$= RIGHT$(A$,2):GOSUB 40900
40220 FORI = 0 TO 1 : POKE PT+I, NC(I+1): NEXT I
40230 RETURN
40299 REM =======
40900 REM CODE THE ARRAY NAME
40901 REM -----
40910 FOR I = 1 TO 2: NC(I)=ASC (MID$ (X$,I,1)): NEXT I
40920 IF NC(2)=32 THEN NC(2)=0
40930 RETURN
40999 REM =======
41000 REM CONFIRM ARRAYS
41001 REM -----
41010 PRINT "DSEQUENCE", "ARRAY XX", "ARRAY YYX"
41020 FORI = 1 TO 20
41030 PRINT RIGHT$ (STR$ (1),2), XX(I), YY(I)
41040 NEXT I
41050 RETURN
41099 REM =======
50000 REM AWAIT VALID KEY
50001 REM -----
50010 GET A$: IF A$="" THEN 50010
50020 FOR I = 1 TO LEN (Z$)
50030 IF As=MIDs (Zs,I,1) THEN RETURN
50040 NEXT I: GOTO 50010
50090 REM ======
50800 REM BUBBLE SORT
```

50801 REM ----50810 PRINT"D#SORTING ARRAY ";T\$
50820 X=19: REM X IS CURRENT BOTTOM
50830 SI=0: REM SI IS SWOP INDICATOR
50840 PRINT"#MMSORTING COUNTDOWN";X;"W " :FOR I = 1 TO X
50850 IF Z(I)<=Z(I+1)THEN 50870
50860 A=Z(I): Z(I)=Z(I+1): Z(I+1)=A:SI=1
50870 NEXT I
50880 IF SI=1 THEN X=X-1: GOTO 50830

READY.

Shell-Metzner Sort

50899 REM =======

W Murcott BSc MBCS

50890 RETURN

In "Printout" in issue 7, Mike Gross-Niklaus mentions the Shell-Metzner sort. This has been around a long time. I first came across it in the mid 1960s, in an Algol work-book from English Electric at Kidsgrove. The acknowledgement given in the work-book says that it was first described by D. L. Shell (Comm. A.C.M. 2 No 7 (1959)). The beauty of this sort, in comparison with many others, is that it is quite "intelligent" in that its speed increases if the raw data has already a degree of order.

READY.

Trace

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"PET users may be interested in my experience with Brett Butler's TRACE routine, published in CPUCN Volume 2 Issue 3. As written, tracing can be slowed down by use of the POKE instruction indicated. This introduces a delay of about 300 milliseconds multiplied by the value POKEd, so that the built-in value of 3 causes execution at about 1 second per line. delay for a value of 1 is rather variable, and is not recommended. A value of 0 corresponds to 256, and gives a delay of about 80 seconds. The delay is not interruptable by use of either the SHIFT or STOP keys, which can be a little frustrating.

By rearranging the TRACE program slightly, it can be made to respond to the SHIFT key at any time, thus giving the effect of a 'single-shot' key by setting a large delay and tapping the SHIFT key to advance to the next instruction. Hold it down for full-speed running. To STOP the program whilst in the delayed state, press RUN-STOP and SHIFT together.

There is a short-cut in the program which can cause the TRACE to miss the start of a new line. It occurs if a GOTO is performed from a line number 256\*K+J (where J is between 0 and 255 and K is any integer) to line 256\*K, e.g. line 260 to line 256, or line 1300 to line 1280.

Users will have noticed that, when TRACE displays a READ statement, the characters

read appear in the displayed line immediately following the READ.

\* \* \* \* \* \* \* \* \*

expression, which yields the number of elapsed days since 1st January 1900 for a date expressed in the form D = day (1-28,29,30 or 31), M = month (1-12)m Y = year (0-99). It produces correct results for all dates from March 1st 1900 onwards (to 29th February 2100, to be precise):-

A one-liner which may be found useful in some applications is the following

D+INT(365.25\*(Y+(M<3))+0.1)+INT(30.6\*(M-12\*(M<3))-31.35)

# Modifications to TRACE to test SHIFT continuously

Changes are underlined.

- 104 DATA 253,208,4,228,254,240,106,133,253, 133,35,134,254,134,36,169
- 120 DATA 3.133.107.165.152.208.10.202, 208,249.136,208,246,198,107,208
- 136 DATA <u>242</u>,32,-54,169,160,160,80,153, 255,127,136,208,250,132,182,132
- 860 DATA 228,78,240,107,133,77,133,82,134, 78,134,83,169,3,133,74,173,4
- 870 DATA 2.208.10.202,208,248,136,208, 245.198,74,16,241.32,-54,169,160
- 1120 PRINT "CHANGE SPEED WITH: POKE"; \$1+119; ", X"

NOTE: The modifications have been tested on an upgraded ROM machine (model 3032) but not an original machine.

Hex-Dec/Dec-Hex

READY.

The following routine was sent to us by R W Brand. It allows conversion from HEX to DEC or DEC to HEX. Press RETURN without an input to jump to the opposite conversion

direction.

The program is a bit long .....maybe somebody can get it down to 6 lines or

```
5 REM来来来来来来来来来来来来来来来来DECIMAL TO HEXADECIMAL AND VICE-VERSA来来来来来来来来来来来来来来来来来来来来
10 CLR:B=0:C=-1:INPUT"HEX########";A$:IFA$="*"GOTO120
20 FORA=LEN(A$)TOISTEP-1:B$=MID$(A$,A,1)
30 IFB$="A"THENB$="10"
40 IFB$="B"THENB$="11"
50 IFB$="C"THENB$="12"
50 IFB#="D"THENE#="13"
70 IFB$="E"THEMB$="14"
30 IFB#="F"THENB#="15"
90 C=C+1:B=B+((16†C)*VAL(B$))
100 MEXT
110 PRINT"DECIMAL IS "B"W":GOTO10
120 CLR:N=16:INPUT"DECIMAL DED DESENT: A:IFA=0GOTO10
130 FORC=1T04:A$(C)="0":NEXT
140 B=B+1
150 C=INT(A/N):A$(B)=STR$((A/N-C)*N):A=C:GOSUB200
160 IFAKNTHENB=B+1:A$(B)=STR$(A):GOSUB200:GOTO180
170 GOTC140
180 A$=A$(4)+A$(3)+A$(2)+A$(1):PRINT"HEX IS ";A$"N"
190 GOTO120
200 IFA$(B)=" 10"THENA$(B)="A":RETURN
220 IFA$(B)=" 12"THENA$(B)="C":RETURN
230 IFA$(B)=" 13"THENA$(B)="D":RETURN
240 IFA$(B)=" 14"THENA$(B)="E":RETURN
250 IFA$(B)=" 15"THENA$(B)="F":RETURN
260 A$(B)=RIGHT$(A$(B),1):RETURN
```

## BASIC REPEAT KEY

This little program gives you the chance of making a very simple repeat key for the PET.

Location 151 (515 old ROM) is used to hold the last key pressed. This location is the keyboard matrix number and while it can be used for fairly simple applications such as cursor control, it is not realistic to use it for ASCII conversion within a program.

The PET uses a ROM based look up table for converting the key matrix into ASCII. This table starts at 59127 (E6F7 hex). By

adding on the key matrix number an ASCII character will be returned.

When the shift key is being pressed location 152 (516) goes from 0 to 1. When this is multiplied by 128 you will obviously get 0 or 128. By ORing this with the result from the PEEK at the lookup table the shifted ASCII characters are produced.

The routine will not work for old ROM PETs due to PEEK protect, but it should be very simple to write a machine code program to perform the above operations and store the result somewhere that can be PEEKed by BASIC.

```
15 REM
20 REM CURSOR REPEAT - PAUL HIGGINBOTTOM - COMMODORE
25 REM
26 REM USE CURSOR CONTROL KEYS TO MOVE *
27 REM
30 REM***************************
40 PRINT" Telefoldialelelelelelelelelelelele
50 A=(PEEK(59127+PEEK(151)))OR(PEEK(152)*128)
55 IFA=253G0T050
60 IFA=17THENPRINT" XIINI";
70 IFA=145THENPRINT"
                   『神味』";
80 IFA=157THENPRINT" INNI";
90 IFA=29THENPRINT" *∰";
100 GOTO50
READY.
```

# **Applications**

A R Clark C D Smith I Kirk Leeds University Physics Dept

FAR INFRARED ASTRONOMY GROUND STATION Using the PET with Interrupts

The schematic overleaf shows the arrangement of a Ground Station to be used later this year in Texas during high-altitude balloon flights.

The slow scan video gives us the star field within an  $8\times 10$  field of view and the star field is updated every 2 seconds.

The 6800 synchronises to the serial data stream and decodes 32 analog words and 8 digital words. Two of the digital words give us our infrared information and the M6800 performs a handshake of 128 bytes of I.R. data every 8 seconds to the PET. (Each handshake taking approximately 100 milliseconds).

Most of the other digital words define the status of our experiment and appropriate statements are displayed on the Kode VDU - the status being upgraded every 4 seconds.

The infrared data is displayed graphically on the PET screen, partially processed and then stored on the Floppy. As the printer takes approximately 15 seconds to print out a full page, we can obtain a hard copy every 3 handshakes.

The following notes give further details of our technique for handshaking data between

the PET and external microprocessor.

## PET - M6800 DATA HANDSHAKE

Figure 1 shows the basic flow diagram for the handshaking of 128 bytes of data from a Motorola M6800 into the PET. The data arrives from the M6800 onto the user port data lines (memory location \$E841), and the interrupt request comes to the memory expansion port which is also connected to a floppy disk. The handshaking routine is designed so that this operation is carried out before the PET services any of its internally-generated interrupts, and resides in the cassette #2 buffer - starting address \$033A (826 decimal). The machine code routine is shown in Figure 2.

In order that the above routine is executed before any internal interrupts, the vector pointer must be reset so that PET jumps directly to \$033A. This could be done directly by the commands: POKE 537,(low order byte): POKE 538, (high order byte), but if an interrupt occurs before the high order byte has been stored, the system will crash. For this reason, the pointer must be reset by the machine code routine shown in Figure 3, which is loaded from BASIC into the top of cassette #2 buffer, and run by a SYS command. If PET is servicing a routine when the M6800 sends IRQ, it will continue with that routine, but IRQ will still be low when it finishes, so PET will service M6800 immediately on completion of the RTI instruction. Hence the M6800 will continue to request until PET acknowledges by sending the 'DATA REQUEST' pulse.

(The handshake routine finishes by storing a flag in \$0377 [887 decimal] which can be tested from BASIC by the PEEK(887) command, always remembering to reset the flag as soon as it has been found.)

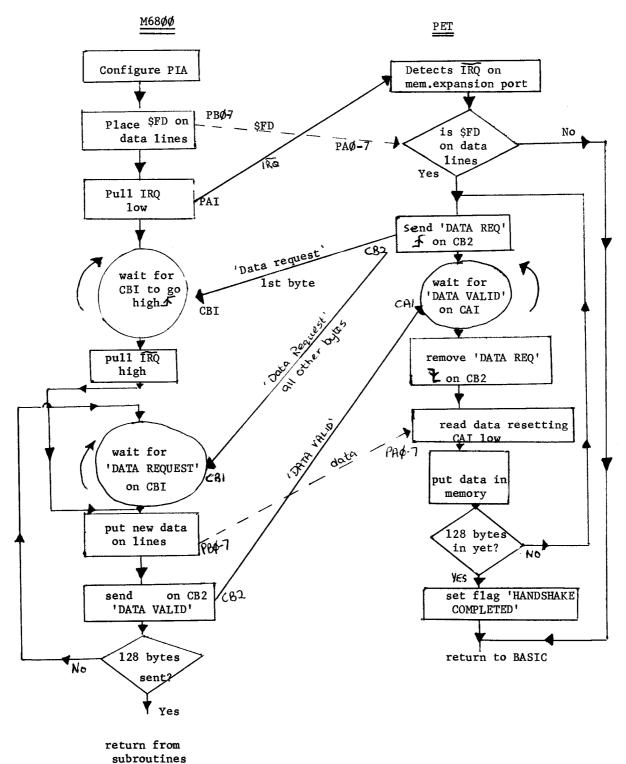


FIGURE 1 Flow chart for data handshaking

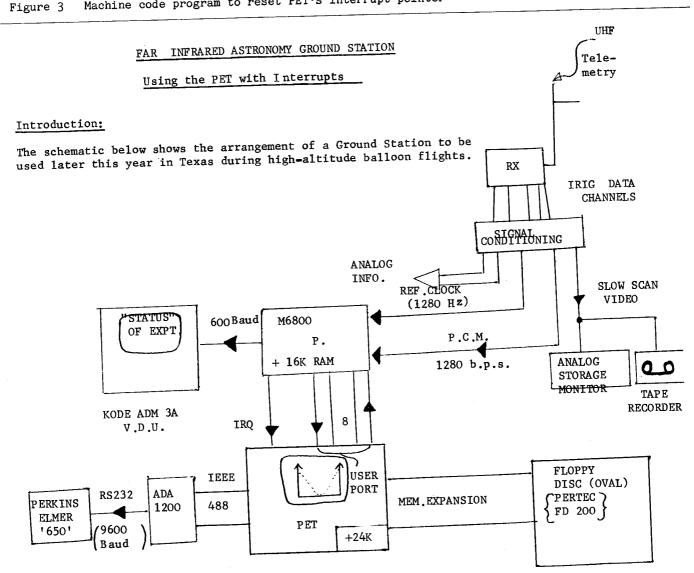
	LDA \$E841 CMP #≯FD BNE EXIT LDY #0	;READ DATA ;IS \$FD ON THE DATA LINES?
L2	LDA #≴E1 ORA ≴E84C	;∲FD ON THE LINES — ; AND ′DATA REQUEST′
L3	STA \$E840 LDA #2 AND \$E84B BEQ L3_	;WAIT FOR 'DATA VALID' ON CAI
	LDA #≢DF	

```
PULL CB2 - REMOVE 'DATA REQUEST'
      $E840
AND
STA
      $E840
                 PUT DATA IN STORE
LDA
      $E841
                 ; RESETTING CAI
      $0378,Y
STA
INY
CPY
      #$80
                 DONE?
      L2
ENE
      #$FF
LDA
                 SET FLAG /HANDSHAKE COMPLETED/
      $0377
STA
                 TO BE TESTED BY BASIC
                 ;RETURN TO BASIC
JMP
      BASIC
```

Figure 2 PET's machine code programme for handshaking

```
SEI
LDA (LOW ORDER BYTE)
STA $0219
LDA (HIGH ORDER BYTE)
STA $021A
CLI
```

Figure 3 Machine code program to reset PET's interrupt pointer



# Beginning machine code

Paul Higginbottom

INSTRUCTION MODES AND 6502 OPERATIONS

You remember last time I left you a program that I said I would let you ponder over, and that I would go over it this time? Well here goes:

The program demonstrated many different principles of 6502 machine code programming, and instruction modes. These will be explained statement by statement.

When I say "instruction mode", this means that there are different modes for different instructions, and, in fact, many instructions can be executed in more than one mode. An example of his is the LDA instruction, used last time. It can be used in the "immediate" mode. This means that the accumulator can be loaded directly with a value, rather than the contents of a memory location. Another mode of the LDA instruction is "absolute". This means that the address is given after the instruction (instead of a value), and the Accumulator is loaded with the contents of the memory at the specified address.

line 1: LDA #\$01 - This is an immediate mode instruction and 'says' :load the accumulator with the value \$01 (the '#' symbol tells the assembler that is a value rather than the contents of memory location \$01 that is to be loaded into the accumulator). Immediate mode means that the value to be used is immediately after the instruction, rather than the contents of a memory location defined by the operand.

line 2: LDX #\$00 - This is also an immediate mode instruction and 'says' :load the X register with the value \$00.

line 3: STA \$8000,X - This is an absolute indexed mode instruction and says: store the contents of the accumulator at the address [\$8000 + the contents of the X register]

line 4: INX - This is an implied mode instruction since the instruction itself defines what register the operation is being performed on. The instruction says:Increment the X register by one.

line 5: CPX #\$28 - This is an immediate mode instruction and says: compare the contents of the X register with \$28

line 6: BNE \$033E - This is an implied mode instruction and says: branch if not equal to the address \$033E. Thus, if the comparison of X and \$28 (or decimal 40) was not equal, i.e X<>40, then branch back to the address \$033E, and continue executing. The BRANCH instructions will be explained fully later in this article.

line 7: RTS - This is an implied mode instruction and says: return from subroutine. This instruction will cause execution of this routine to cease, and

return to where it was executed from. As this was a SYS call, then it will return to a usual basic 'ready' mode.

In the processor, there are many registers, some I have already mentioned. I think that now would be a good time to describe those registers.

ACCUMULATOR - This is the main eight bit register, around which most of the instructions are based.

X register - This is an eight bit index register. 'Index' means that it can be used to offset a base address by its contents. This was shown in the first program.

Y register - This is also an eight bit index register and has similar facilities as the X register. However some 6502 instructions are designed only for use with the X or the Y registers but not both.

Status register - This is possibly the most valuable and vital register in the processor. It uses each of its eight bits to describe a state that has arisen by one instruction, or by a sequence of instructions.

Each bit will be described below:-

NVBDIZC

N - Negative Flag.

This is set if a negative condition is made. This could be done with a subtraction, decrement, comparison or some other instruction. There are no instructions to set it directly. (The comparison instruction, does an internal subtraction and sets the flags according to the result of the subtraction). BMI (branch on minus) will take the branch if the negative flag is set.

V - Overflow Flag.

This is set if a result actually overflowed the register being operated on, e.g if a value is added to a register that makes it go over \$FF (or 255 decimal), then the value in the register would be the result-256, and this might make mathematical calculations go wrong, and so the overflow flag is set. It may be cleared directly with the instruction CLV (clear overflow flag). It may be detected by the instructions BVC (branch on overflow clear) and BVS (branch if overflow set).

B - BRK command executed.

This is set if the BRK (break) instruction is executed. It would not be worthwile covering this at the moment.

D - Decimal mode flag.

This is set and cleared by SED and CLD (set, and clear decimal mode) instructions. If decimal mode is set, then the add and



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CREATE

KCS="CREATE O:MAILFILE,120,15,1: SYS 24576
This example tells KRAM to create an indexed file called
MAILFILE on the disk in drive zero, with a record length of 120 characters
and a key length of 15 characters which starts at position 1 of the record.
KRAM looks at the RESERVED variable KCS to identify the function and its
parameters; the SYS call tells KRAM to execute the function. The record
length can be any value up to 254 characters and the key up to 48 characters,
a total of 302. KRAM packs as many records into the 255 character disk block
as necessary.

OPEN

KCS="OPEN O:MAILFILE": SYS 24579 This tells KRAM that we will want to make accesses to the file called MAILFILE on the disk in drive zero. KRAM returns in location zero (peek (0)) the file number by which this file can be accessed during the rest of the program.

ADD KCS="ADD 1.NA\$,AD\$": SYS 24591 This tells KRAM to add to file number one the data in variable AD\$ whose key is NA\$. For example in a mailing list, the key NA\$ might be the name 'SMITH AJ.' and AD\$ might be the address '120, HIGH STREET, ANYTOWN'. Any normal double character string variable can be used to denote the key and the record.

GET

KCS="GET 1,NAS,ADS": SYS 24582 This tells
KRAM to get from file number one the data belonging
to the key NAS and put it into variable ADS. In our example, if NAS was
'SMITH A. J.', KRAM would read the address '120, HIGH STREET,
ANYTOWN' from file and put it into variable ADS. If we weren't sure of the
exact surname, we could give KRAM the key 'SM' and it would get for us the
next alphabetically higher name beginning 'SM', together with its address! Or if
we gave KRAM a blank key, it would find the first name and address on file.

READ KCS="READ 1.NAS.ADS": SYS 24585 This tells KRAM to read the data belonging to the next highest key following the name in NAS, and put it into variable ADS. In our example, a complete file of names and addresses could be read in alphabetical order, starting at any name in the file, simply by executing successive READ commands! For instance, having got Mr A. J. Smith from file, executing the READ command as above would get us say 'SMITH M.' in NAS together with his address in ADS.

READ - KCS="READ-I NAS, ADS": SYS 24585 This works like READ except BACKWARDSI It tells KRAM to read the data belonging to the next lowest key preceding the name in NAS, and put it into ADS. For instance, having read "SMITH M." with the forward read, executing the backward read as above would get us "SMITH AJ." in NAS together with his address in ADS.

PUT KC\$="PUT 1,NA\$,AD\$": SYS 24588 This tells KRAM to rewrite to file number one the data in variable AD\$ which belongs to key NA\$. For instance, if we wanted to change Mr A.J. Smith's address, we would simply set NA\$ equal to 'SMITH A.J.', AD\$ equal to his new address, and execute the PUT function.

DELETE KCS="DELETE 1.NA\$,AD\$": SYS 24594 This tells KRAM to delete from file number one the key contained in NA\$ and its associated data contained in AD\$. In our example, to delete Mr A. J. Smith from the file, we would simply set NA\$ equal to 'SMITH A.J.', AD\$ equal to his address, and execute the DELETE function. KRAM will release for further use the disk space made available by the deletion.

CLOSE

KCS="CLOSE 1": SYS 24597 This tells KRAM that file one is finished with for now. KRAM updates the BAM on disk, but the file can still be used without another OPEN command.

INITIALIZE SYS 24600 This function is used at the beginning of each program to clear KRAM's work areas and buffers.

The examples above illustrate the use of KRAM in a mailing list application, with disk access times from less than one second. KRAM can of course be used in any application program with the Commodore disk where programmer time, user time and disk space are at a premium.

Each KRAM package includes a ROM which plugs into the middle ROM socket of the 16K/32K Pet, a demonstration disk with a mailing list program and a 40-page User Reference Manual. KRAM is available by post (cash with order) price £115 including VAT, or by credit card phone the KRAM 24 Hour Order Desk on 01-546 7256; or see your nearest dealer. (Quantity discounts available).

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Mike Gross-Niklaus Training Manager Commodore Business Machines 360 Euston Road London NW1 3BL subtract instructions work in a different way. The results are left in BCD (binary coded decimal).

Decimal mode off.

3 9 (base sixteen - HEX)

0011 1001 = 57 in decimal.

Decimal mode on.

5 7 (base ten - decimal)

 $0101 \quad 0111 = 57 \text{ in decimal}$ 

As can be seen, all that happens is that the result is transformed to leave the first decimal digit in the first four bits, and the second, the upper four bits. This is useful for decimal output, rather than binary or hex.

#### I - Interrupts disabled flag.

This is set if the SEI (set interrupt disabled flag) is executed, and reset if the CLI (clear interrupt disabled flag) instruction is executed. It would not be worthwile covering this at the moment.

#### Z - Zero flag.

This is set when any instruction leaves a register with 0 in it. It cannot be set or reset directly. It can be detected with the BEQ (branch if equal), and BNE (branch if not equal) instructions.

#### C - Carry flag.

This can be thought of as a ninth bit to any register. It can be manipulated directly with the SEC (set carry) and the CLC (clear carry) instructions. It can be detected by the BCC (branch if carry clear) and BCS (branch if carry set) instructions. If 2 two byte (16 bit) values are to be added, and stored in a result, then it is necessary to detect a carry from the first addition of the two low bytes, which should be added to the result of the addition of the two high bytes. An example of this would be as follows:-

Imagine we have two 16 bit values stored in the locations FRED, and BERT. This value is of course split into two 8 bit values. So we have the first value in FRED and FRED+1, and the second in BERT and BERT+1. To add these two values and store the result in JOE and JOE+1, the following code is necessary:-

; CLEAR CARRY FLAG TO CLC ;START WITH ;LOAD THE ACCUMULATOR LDA FRED ; WITH THE CONTENTS OF ; FRED ; THIS IS OF COURSE ONLY ;THE FIRST 8 BITS OF ; ADD WITH CARRY THE ADC BERT CONTENTS OF BERT ; AND STORE THE RESULT STA JOE ; IN JOE ;LOAD THE UPPER 8 BITS LDA FRED+1 :OF FRED ADC BERT+1 ; ADD WITH THE CARRY THE STA JOE+1

;UPPER 8 BITS OF BERT; AND STORE THE RESULT IN; THE UPPER 8 BITS OF JOE

At this point it becomes necessary to define what is available to us within the 6502 microprocessor, and its storage. The 6502 uses 2 bytes for each address apart from those in the range \$0000 to \$00FF (256) bytes, which do not need a high byte to describe their address, because in that range it is always zero. As was stated in the last article, each block of 256 bytes is known as a page of memory. The first 256 bytes (\$0000 - \$00FF) are known as page zero locations and there is a mode of instruction called simply 'zero page'. This mode tells the processor that it only need pick up one byte for the address.

The 6502 also has what is known as a 'stack', which is used by the processor as well as the programmer. This uses the whole of page one memory (that is \$0100 - \$01FF). I will try to explain simply what the stack is used for. When doing a GOSUB instruction in BASIC, this tells the Pet to jump to a given line number and when a RETURN instruction is found it must return to the statement following the GOSUB instruction. So, at the time the GOSUB instruction was encountered, it must have some way of remembering where it currently is in memory, so that it knows where to RETURN to. There are instructions PHA (push accumulator on stack), PHP (push processor status register on the stack), PLA (pull accumulator off stack), and PLP (pull processor status off stack), which work with an eight bit register inside the processor called a stack pointer. Each time a PHA instruction is done, the contents of the accumulator will be put at \$0100 offset by the stack pointer, and the stack pointer will be automatically deceremented by one, so that the next push will put the data onto the next position on the stack etc. Correspondingly, the PLA instruction will load the accumulator with the contents of the memory whose address is \$0100 offset by the stack pointer, and the stack pointer will be incremented by one etc. N.B The movements of the stack pointer also apply with the PHP and PLP commands. Going back to our GOSUB instruction, by using the instructions just described, the PET may use the stack to save its current position when going off to the subroutine. When a RETURN instruction is encountered, it simply 'pulls' off the stack the point at which it was before entering the subroutine and moves onto the next instruction as if nothing had happened. This explains why there is a maximum level to 'nesting' of subroutines (i.e one subroutine calling another, which in turn calls another etc.), because the stack is of a fixed size and as each set of return data is pushed onto the stack, the stack slowly gets filled up, until an ?OUT OF MEMORY ERROR occurs. You can demonstrate this to yourself by typing in the basic program

10 C=C+1:GOSUB10 <RETURN> RUN <RETURN>

The pet should (after a little while) display ?OUT OF MEMORY ERROR IN 10. If you print the value of C, this will tell you the number of levels of subroutine you had got up to before the stack was filled. The pet does in fact check to see if the stack will be over filled by the next instruction. If it didn't, then the pet would probably hang itself up. Fortunately MICROSOFT (the authors of the basic interpreter in the pet) thought of that. Right then, we've discussed the stack, and how useful that is, I think I should explain the BRANCH instructions fully now, and I will leave another program for you to look at.

BEQ - Branch if equal, meaning branch if zero flag set.

BNE - Branch if not equal, meaning branch if zero flag not set.

BCC - Branch if carry clear. BCS - Branch if carry set.

BVC - Branch if overflow clear.

BVS - Branch if overflow set.

BMI - Branch if negative result, branch if negative flag is set

BPL - Branch if positive result, branch if negative flag is not set

Program to rotate the screen left one byte.

We shall write this one in standard assembler format.

> ; PROGRAM STARTS AT \* =\$033A ;\$033A ;LOAD ACCUMULATOR WITH LDA #\$00 :THE VALUE '\$00'. ;STORE IT IN MEMORY STA \$01 ;LOCATION \$01 ;LOAD ACCUMULATOR WITH LDA #\$80 ; THE VALUE '\$80'. ;STORE IT IN MEMORY STA \$02 ;LOCATION \$02

(HERE I HAVE SET UP IN LOCATIONS 1 AND 2 THE 16 BIT ADDRESS OF THE START OF THE SCREEN - \$8000. BYTES 1 AND 2 WILL BE USED AS A 16 BIT POINTER TO THE CURRENT LOCATION ON THE SCREEN BEING MOVED)

> ;LOAD ACCUMULATOR WITH LDA #\$19 ; THE VALUE 25 (DECIMAL) ;STORE IT IN MEMORY STA \$00 ;LOCATION \$00

(HERE I HAVE SET UP IN LOCATION O A SCREEN LINE COUNTER. I HAVE SET IT TO 25 AND EACH TIME I ROTATE A ROW OF THE SCREEN, I WILL DECREMENT THIS COUNTER, AND STOP WHEN IT REACHES ZERO)

; ZEROISE OFFSET TO START LDY #0 : POINTER ; IN 1 AND 2

;LOAD THE ACCUMULATOR LDA (\$01),Y ;WITH

; THE CONTENTS OF THE ; ADDRESS

; POINTED TO BY THE ;BYTES \$01

; AND THE NEXT ONE

;(\$02) ;OFFSET BY THE ; CONTENTS OF THE ;Y REGISTER

; PUSH THE CONTENTS OF ; THE ACCUMULATOR ONTO ; THE STACK. SINCE ;THIS IS THE FIRST ; CHARACTER IN THE ROW, ; WE WILL SAVE IT. THEN ; PULL THE OTHER 39 ; CHARACTERS BACK ONE ; POSITION, AND PULL :THIS VALUE ;BACK OFF THE STACK, : AND PUT IT AT THE

END OF THE ROW ; INCREMENT THE OFFSET INY

;BY ONE

PHA

LDA (\$01),Y ;GET A CHARACTER FROM LOOP ; THE ROW

; DECREMENT OFFSET TO DEY ;STORE THIS CHARACTER ; IN THE PREVIOUS

; POSITION STA (\$01),Y ; PUT IT BACK ON THE

:SCREEN ; INCREMENT Y TO WHAT

INY ; IT WAS

MOVE ONTO THE NEXT TNY

;SQUARE

HAVE WE REACHED THE CPY #\$28 ;LAST POSITION ON THE

;LINE ? I.E HAS THE

:OFFSET ;GOT TO 40 (DECIMAL)

; IF NOT - GO BACK AND BNE LOOP

; DO IT AGAIN ; WE HAVE - SO PUT PLA ;SAVED CHARACTER

BACK ONTO THE SCREEN ; PULL BYTE OFF STACK ; INTO THE ACCUMULATOR ; RESET OFFSET TO LAST

DEY ; POSITION

; PUT IT IN THE LAST STA (\$01),Y ; POSITION

; DECREMENT LINE COUNT DEC \$00 ; IF EQUAL TO ZERO -BEQ EXIT

;THEN EXIT CLEAR CARRY CLC ;OTHERWISE - BUMP LDA \$01 ; POINTER BY 40

; ADD \$28 TO LOW BYTE ADC #\$28 ; AND STORE RESULT STA \$01 ;GET HIGH BYTE LDA \$02 ; ADD NOTHING + THE ADC #\$00 ; CARRY

; JUMP BACK TO THE

:START :FINISHED - RETURN EXIT RTS

JMP START

:FROM SUBROUTINE There you go. Have a look at this until

next newsletter, when I will explain how it works.

Bye.

# Supermon

## SUPERMON - OLD ROM VERSION

David A Hills

Here is a chance for those of you with the OLD ROM 8K PET to have a go with the superb SUPERMON program. The TIM monitor has been included in with SUPERMON so once it's been entered you should be able to put TIM into

## SUPERMON

Modified for use with Old ROMs by: D.A. Hills,
19, St. Anthonys Drive,
Chelmsford,
Essex.

Monitor is entered by SYS(6726) Exit to BASIC by .X Save on tape with :-.S 01, SUPERMON(0),16F6,2000

16F0 AA AA AA AA AA AA A9 06

16F8 8D 1B 02 A9 17 8D 1C 02 1700 A9 43 85 21 D0 12 A9 42

1708 85 21 D8 4A 68 85 1E 68

1710 85 ID 68 85 IC 68 85 IB

1718 68 69 FF 85 19 68 69 FF

1720 85 1A BA 86 1F 58 20 BC 1728 17 A6 21 A9 2A 20 EC 18

1730 A9 52 85 0D D0 1B A9 00 1738 85 CA 85 0D 85 0A 20 BC 1740 17 A9 2E 20 D2 FF 20 5A

1748 19 C9 2E F0 F9 C9 20 F0 1750 F5 A2 07 DD CC 17 D0 0F 1758 A5 20 85 0E 86 20 BD D4

1768 10 E9 4C 5D 1A 38 A5 13

1770 E5 11 85 0B A5 14 E5 12 1778 A8 05 0B 60 A5 11 85 19

1780 A5 12 85 1A 60 85 21 A0 1788 00 20 04 19 B1 11 20 DD

1790 18 20 C1 17 C6 21 D0 F1

1798 60 20 28 19 90 0D A2 00

17A0 81 11 C1 11 F0 05 68 68

17A8 4C 65 17 20 C1 17 C6 21

17B0 60 A9 1B 85 11 A9 00 85 17B8 12 A9 05 60 A9 0D 4C D2

17C0 FF E6 11 D0 06 E6 12 D0

17C8 02 E6 0A 60 3A 3B 52 4D 17D0 47 58 4C 53 18 18 17 18

17D8 18 18 19 19 8B 7B F6 28 17E0 A1 C7 68 68 20 50 43 20 17E8 20 53 52 20 41 43 20 58

17F0 52 20 59 52 20 53 50 A5

17F8 0D D0 06 20 BC 17 20 01

1800 19 20 01 19 A2 00 BD E4

1818 20 EC 18 20 01 19 20 D2

1828 4D 20 5A 19 20 19 19 90

1830 48 20 09 19 20 5A 19 20

1838 19 19 90 3D 20 09 19 A0

1840 00 B9 14 1A 30 06 20 D2 1848 FF C8 D0 F5 29 7F 20 D2

1850 FF 20 2A F3 F0 20 A6 0A

1858 D0 1C 20 6D 17 90 17 20

1860 BC 17 A2 2E A9 3A 20 EC

17

20 D2 FF

20 BC

1820 18 20 B1 17

1808 17

1810 F5

17 48 60 CA

E8 E0 13 D0

A2 2E A9 3B

20 85 17 F0

1760 17 48 BD DC

honourable retirement. All of the commands for SUPERMON are the same, as given in CPUCN Vol. 2 Issue 3.

Save SUPERMON using the TIM SAVE command from 16F6 to 2000.

To enter the program when it has been loaded type: SYS 6726.

```
1868 18 20 01 19 20 CE 18 A9
     1870 08 20 85 17 F0 DB 4C 36
1878 17 4C 65 17 20 28 19 20
.: 1880 19 19 90 03 20 7C 17 20
     1888 B1 17 D0 0A 20 28 19 20
. :
     1890 19 19 90 E5 A9 08 85 21
     1898 20 5A 19 20 99 17 D0 F8
.: 18A0 F0 D4 20 CF FF C9 0D F0
.: 18A8 0C C9 20 D0 CC 20 19 19
     18B0 90 03 20 7C 17 A6 1F 9A
.: 18B8 A5 1A 48 A5 19 48 A5
     1800 48 A5 10 A6 1D A4 1E
1808 A6 1F 9A 40 8B 03 A2
                                    91
     18D0 D0 02 A2 09 B5 10 48 B5
   - 18D8 11 20 DD 18 68 48 4A 4A
   18E0 4A 4A 20 F5 18 AA 68 29
    18E8 0F 20 F5 18 48 8A 20 D2
18F0 FF 68 4C D2 FF 18 69 06
     18F8 69 F0 90 02 69 06 69 3A
    1900 60 20 04 19 A9 20 4C D2
    1908 FF A2 02 B5 10 48 B5 12
    1910 95 10 68 95 12 CA DO F3
   1918 60 20 28 19 90 02 85 12
                             85 11
     1920 20 28 19 90 02
     1928 A9 00 85 0F
                         20 5A 19 C9
     1930 20 DO 09 20 5A 19 C9
                                    20
   1938 DO OE 18 60 20 4F 19 OA
    1940 0A 0A 0A 85 0F 20 5A 19
   1948 20 4F 19 05 0F 38 60 C9
1950 3A 08 29 0F 28 90 02 69
1958 08 60 20 CF FF C9 0D D0
    1960 F8 68 68 4C 36
1968 17 20 5A 19 A9
                            00 85
                                    EE
     1970 85 FA A9
                     23 85
                            F9 20 28
                             20 5A
     1978 19 29
                  ØF 85
                         F1
     1980 A2 00 20 CF FF C9 2C F0
    1988 55 C9 ØD FØ ØB EØ 10 FØ
.:
     1990 F1 95 23 E6 EE E8 D0 EA
1998 A5 20 C9 06 D0 C8 A2 00
    19A0 8E 0B 02 A5 F1 D0 03 4C
     19A8 65 17 C9 03 B0 F9 20 67
    19B0 F6 20 3B F8 20 FF F3 A5
     19B8 EE F0 08 20 95 F4 D0 08
     1900 40 65 17 20 AE F5 F0 F8
1908 20 4D F6 20 22 F4 20 8A
.:
     19D0 F8 20 13 F9 AD 00 02 29
     19D8 10 D0 E5 4C 36 17 20 19
```

```
| Fig. 12 | Fig. 22 | Fig. 23 | Fig.
```

1EA8 10 3D CA CA 8A A4 23 D0 1EB0 03 B9 12 00 91 11 88 D0 1EB8 F8 A5 0A 91 11 20 6D 1C 1EC0 85 11 84 12 A0 41 20 38 1EC8 1A 20 CE 18 20 04 13 4C 1ED0 DE 1D 20 D5 1E 86 20 A6 1ED8 21 DD 31 00 F0 0C 68 63 1EE0 E6 0A F0 03 4C 30 1E 4C 1EE0 C9 30 90 03 C9 47 60 38 1EF0 C9 30 90 03 C9 47 60 38 1EF0 09 30 22 45 33 D0 08 40 1F00 09 30 22 45 33 D0 08 40 1F10 09 40 02 45 B3 D0 08 40 1F10 09 40 02 45 B3 D0 8C 44 1F20 00 11 22 44 33 D0 8C 44 1F20 00 11 22 44 33 D0 8C 44 1F20 00 10 22 44 33 D0 08 40 1F30 09 10 22 44 33 D0 08 40 1F30 09 10 22 24 33 D0 08 40 1F38 09 62 13 78 A9 00 21 81 1F40 82 00 00 59 4D 91 92 86 1F48 4A 85 9D 2C 29 2C 23 28 1F50 24 59 00 58 24 24 00 1C 1F58 8A 1C 23 5D 8B 1B A1 9D	1F60 8A 1D 23 9D 8B 1D A1 00 1F68 29 19 AE 69 A8 19 23 24 1F70 53 1B 23 24 53 19 A1 00 1F78 1A 5B 5B A5 69 24 24 AE 1F80 AE A8 AD 29 00 7C 00 15 1F88 9C 6D 9C A5 69 29 53 84 1F90 13 34 11 A5 69 23 A0 D8 1F90 14 3 34 11 A5 69 23 A0 D8 1F90 14 A8 54 68 44 E8 94 00 1F90 44 C8 54 68 44 E8 94 00 1FA8 B4 08 84 74 B4 28 6E 74 1FB0 F4 CC 4A 72 F2 A4 8A 00 1FB8 AA A2 A2 74 74 74 72 44 1FC0 68 B2 32 B2 00 22 00 1A 1FC8 1A 26 26 72 72 88 C3 C4 1FD0 CA 26 48 44 44 A2 C3 04 1FD0 CA 26 48 44 44 A2 C3 04 1FD0 CA 26 48 44 44 A2 C3 04 1FD0 CA 26 A8 44 44 A8 60 1FE0 48 44 43 2C 41 49 4E 00 1FE0 48 44 43 2C 41 49 4E 00 1FE0 FD 1C 30 1D DA 1D 54 1D 1FE0 FD 1C 30 1D DA 1D 54 1D 1FF0 FD 1C 30 1D DA 1D 54 1D 1B 1FF0 FD 1C 30 1D DA 1D 54 1D 1B 1FF0 FD 1C 30 1D DA 1D 54 1D 1B 1FF0 FD 1C 30 1D DA 1D 54 1D 1B 1B 1FF0 FD 1C 30 1D DA 1D 54 1D 1B 1B 1FF0 FD 1C 30 1D DA 1D 54 1D 1B
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#### EDUCATION NEWS

## Regional Educational Conferences

We are pleased to announce that we will be putting on conferences for teachers in Glasgow, Manchester, Birmingham, Bristol and London in mid September.

Further details will be included in the next issue of CPUCN and the new addition of Microcomputers in Schools and Colleges.

Admission to the conference will be free.

Topics to be covered will include, Software development for the classroom and first hand accounts of experiences with the Pet. We would like to contact teachers who are using a Pet in these areas with a view to them contributing to the conference.

Teachers who would like to give a short paper at the conference, are asked to contact:

CBM Ltd., Nick Green 360 Euston Road, London, W.1.

#### Free Workshop Software

If you are using Pets in your school, college or university, and teachers in your area are using these Pets, for example, out of school hours for software development purposes or training, we will send you on cassette tape some 43 programs from North America and Canada. The programs cover a wide range of ages and subject matters and some are written to a very high standard indeed. Others you will be less impressed with! These programs maybe modified in any way you wish and distribited in any way you wish. We hope that they will inspire you to new heights. In a few months time we hope to have collected from you improved versions and indeed new programs that you would like distributed in the same way.

	Does your Institution offer courses to teachers:
Please send me free Workshop Software 1. We are allowing teachers in our area access to Pets, when not in use, for Workshop purposes:	If so, please give details below:
NAME:	
ADDRESS:	
NO. OF PETS:	
PERIPHERALS:	
AVAILABILITY OF PETS:	Would you be interested in attending a free one-day course on Pet Architecture in London for Workshop organizers?
a) Dates	
	Please fill in the above and send to:
h) Timag	_

The PET/CMB computer has been around for over two years and, in that time, various changes have been made to the system software stored in the ROMs. To bring you up to date and clarify any confusion that may have been caused by the number of different ROM sets, we are publishing the following list with explanations.

When the PET 2001 first went into production, there were two ROM Sets incorporated into the system. One ROM Set is the 6540 type ROM. This is a 28 Pin Rom which is manufactured by MOS Technology, Inc. You will find these ROMs in the following locations on the PET 2001-4K and 2001-8K Main Logic Board:

Location	<u>ROM</u>	Part Number
H1	6540-019	901439-09 or 01
H2	6540-013	901439-02
H3	6540-015	901439-03
H4	6540-016	901439-04
H5	6540-012	901439-05
H6	6540-014	901439-06
H7	6540-018	901439-07
A2	6540-010	901439-08

NOTE: There is an 019 ROM at the H1 location. On some earlier Main Logic Boards you will find a 6540-011 at H1. This ROM has been updated to an 019 due to an intermittent bug in the edit software. This ROM Set is Basic level 1.

The other ROM Set incorporated into the PET 2001 is a type 2316B 24 Pin ROM. You will find these ROMs in the following locations on the PET 2001-4K and 2001-8K Main Logic Board:

Location	ROM	Part Number
H1 H2 H3 H4 H5 H6 H7 A2	901447-09 901447-03 901447-05 901447-06 901447-02 901447-04 901447-07 901447-08	901447-09 901447-03 901447-05 901447-06 901447-02 901447-04 901447-07

NOTE: There is an 09 ROM at the H1 location. On some earlier Main Logic Boards you will find a 901447-01 ROM. This ROM has been updated to an 09 ROM due to an intermittent bug in the edit software. Like the 6540 ROM Set, this too is a Basic Lever 1 ROM Set. To determine what the 6540 and 2316B ROMs listed above are capable of, I would refer you to the "PET User Manual" Model 2001-8.

The next two ROM Sets are Basic Level II ROMs, and are fitted as standard on all 16 and 32K PET/CBMs. They are also Retrofit Kits for the 2316B and 6540 Basic Level 1 ROMs. The Basic Level II ROMs include the machine language. Basic Level II allows you to interface the Commodore 2040 Dual Floppy to your PET/CBM. Basic Level I ROMs will not allow you to interface the 2040 Dual Floppy to your PET. The Basic Level

II Retrofit ROMs also allow you to use arrays with more than 255 elements.

If your PET/CBM has the Basic Level I 6540 ROMs, you could use the following ROMs which come in the form of a Retrofit Kit to upgrade your PET/CBM to Basic Level II.

Location	<u>ROM</u>	Part Number
Н1	6540-020	901439-13
H2	6540-022	901439-15
Н3	6540-024	901439-17
H4	6540-025	901439-18
H5	6540-021	901439-14
н6	6540-023	901439-16
H7	6540-026	901439-19

If your PET/CBM has the Basic Level I 2316B ROMs, you would use the following ROMs which come in the form of a Retrofit Kit to upgrade your PET/CBM to Basic Level II:

<u>Location</u>	ROM	Part Number
H1 H2 H3 H4 H5 H6 H7	901465-01 901465-02 901465-24 901465-03 Blank Blank Blank	901465-01 901465-02 901465-24 901465-03

The following ROM Sets are the ROMs that are currently being used in production. There are two sets of ROMs in use. If you have a graphic style PET, you should have the following ROMs in your unit:

Location	ROM	Part Number	
D3	Blank		
D4	Blank		
D5	Blank		
D6	901465-01	901465-01	
D7	901465-02	901465-02	
D8	901447-24	901447-24	
D9	901465-03	901465-03	
F10	901447-10	901447-10	

If your computer is a business style, you should have the following ROMs in your unit:

Location	ROM	Part Number
D3	Blank	
D4	Blank	
D5	Blank	
D6	901465-01	901465-01
D7	901465-02	901465-02
D8	901447-01	901447-01
D9	901465-03	901465-03

The ROMs in the graphic and business PET/CBM are Basic Level III ROMs. To determine what any machine fitted with Basic Level III is capable of, you should refer to the "CBM User Manual" Model 2001-16, 16N, 32, 32N.

The ROMs currently being used in production of the 3040 Dual Floppy are as follows:

Location	ROM	Part Number	dos2.1.
UL1 UK1 UH1 UK3	901468-06 Blank 901468-07 6530-02	901468-06 901468-07 901466-02	New BASIC eliminates garbage collection problems and has a powerful direct access feature which considerably enhances the disk system.
			to a decide a mimbe

These ROMs are DOS Version I.

New 80 column PET BASIC 4.0 DOS 2.1 Retrofit ROMs will be available in about 60 days time at £38.00 BASIC 4.0, £38.00 BASIC has been extended to include a number of D.U.M. (Disk Utility Maintenance) features, considerably improving "User Friendliness". DOS 2.1 simply enables the new commands to be recognised.

# NEW ROM TO OLD ROM CONVERSION TABLES FOR PAGE ZERO

NEW PET DEC	NEW PET HEX	OLD PET DEC	OLD PET HEX	FUNCTIONS
0	\$0000-\$0002		T	POKE LOCATION CHANGE
1-2	\$0000-\$0002	1-2	\$0000-\$0002	USER FUNCTION ADDRESS LO; HI
3.	\$0003	90	\$005A	GENERAL COUNTER FOR BASIC SEARCH [SEARCH
3.	•			CHRTR-USUALLY ':' OR ENDLIN]
4.	\$0004	91	\$005B	;00 USED AS DELIMITER [SCAN BETWEEN
				QUOTES FLAG]
5.	\$0005	92	\$005C	GENERAL COUNTER FOR BASIC [INPUT BUFFER
				PNTR][# OF SUBSCRIPTS] FLAG TO REMEMBER DIMENSIONED VARIABLES [1ST
6.	\$0006	93	\$005D	FLAG TO KEWEWBER DIMENSIONED ANTIBERS FIRE
				CHAR OF ARRAY NAME] FLAG FOR VARIABLE TYPE O=NUMERIC;1=STRING
7•	\$0007	94	\$005E	FLAG FOR VARIABLE TIPE OFNORMATO, I-STATEM
				[\$FF STRING] FLAG FOR INTEGER TAPE [80=INTEGER;
8.	\$0008	95	\$005F	
				OO=FLOATING POINT FLAG TO CRUNCH RESERVED WORDS [DATA SCAN
9.	\$0009	96	\$0060	FLAG TO CRUNCH RESERVED WORDS [DATA BOAR
-				FLAG/LIST QUOTE FLAG]
10.	\$000A	97	\$0061	FLAG WHICH ALLOWS SUBSCRIPTS IN SYNTAX
				[FN X FLAG]
11.	\$000B	98	\$0062	FLAG INPUT OR READ [0=INPUT;64=GET;152=READ]
12.	\$000C	99	\$0063	FLAG SIGN OF TAN [FLAG FOR TRIG SIGNS/
				COMPARSN EVALUATION FLAG
13.	\$000D	100	\$0064	FLAG TO SUPPRESS OUTPUT [+=NORMAL;
				-=SUPPRESSED]
14.	\$000E	3	\$0003	ACTIVE I/O CHANNEL [PROMPT-SUPPRESS]
15.	• • • • •	6	••••	TERMINAL WIDTH (UNUSED) LIMIT FOR SCANNING SOURCE [COLUMNS UNUSED]
16.	••••	7	1	LINE NUMBER BEFORE STORAGE [INTEGER ADDRESS
17-18	\$0011-\$0012	8-9	\$0008-\$0009	FROM BASIC
			40065	INDEX TO NEXT AVAILABLE DESCRIPTOR [VARIBL
19.	\$0013	101	\$0065	DESCRPTR STACK PNTR]
			1	
20-21	\$0014-\$0015	102-103	\$0066-\$0067	[SECOND DESCRPT PONTER]
			4006 P #0070	TOTAL PROPERTY OF THE PROPERTY OF THE PARTY
22-29	\$0016-001E	104-111	\$0068-\$0070	TO VARIABLES
_				[DESCRIPTOR STACK FOR TEMPORARY STRINGS]
	*************	440 440	**************************************	INDIRECT ADDRESS #1 LO; HI [POINTER FOR NUMBER
30-31	\$001F-0020			TRANSPER I
	±0004 ±0000	44h 44E	400724007 <i>)</i> 1	INDIFFECT INDEX #2 LO:HI [NUMBER POINTER]
32-33	\$0021-\$0022	114-115	\$0075_\$0078	INDIRECT INDEX #2 LO; HI [NUMBER POINTER] PSEUDO REGISTER FOR FUNCTION OPERANDS
34-39	\$0023-\$0027 \$0028-\$0029	10-121	\$007 A-\$007 B	POINTER TO START OF BASIC TEXT AREA LO; HI
40-41			\$007 C-\$007 D	
42-43	\$002A-\$002B	124-123	ψ0010-ψ0012	BASTC/START VARBL]
to be to co	\$002C-\$002D	126-127	\$007 E-\$007 F	
44-45	<b>∌</b> 0020 <b>~ ∌</b> 002⊅	120-121	4001 H-4001 T	START ARRAYS]
146 147	4000F 4000F	128-129	\$0080-\$0081	TO TOUR DE LES ANT ANY NO. LOUIT COMMON OF
46-47	\$002E-\$002F	120-129	φυσου-φυσοι	AVAILBL SPACE PTR]
110 110	\$0030-\$0031	130-131	\$0082-\$0083	
48-49	\$0020 <del>-</del> \$0031	130-131	40002 40003	STRINGS (MOVING DOWN)]
50 51	\$0032-\$0033	132-133	\$0084-\$0085	THE PART OF THE PA
50-51	\$0032-\$0033	132-133	<b>4</b> 0001-40003	DOWN]
50 50	4002H 4002E	134-135	\$0086-\$0087	TORON OF THE PROPERTY OF THE P
<b>52-5</b> 3	\$0034-\$0035	134-133	ψυσυσ-φυσυ1	MEMORY]
-1	#N036 #0037	136-137	\$0088-\$0089	THE PARTY OF THE P
54-55	\$0036~\$0037	120-121	φυσυσ-φυσυς	DIRECT)[CURRENT LN #]
E6 E7	\$0038-\$0039	138-139	\$008A-\$008E	TO THE
56 <b>-</b> 57	<b>あ</b> いつらーあいりろり	130-139	Ψ00011-Ψ0001	# SAVED BY END]
E8 E0	\$003A-\$003E	3 140-141	\$008C-\$008I	
58 <b>-</b> 59	φυυ3 <b>ν-</b> φυυ3τ	, 170-171	+0000 +000	FOR CONT]
				-

	\$003C-\$003D		****	DATA LINE# FOR ERRORS LO; HI [LINE# OF DATA LINE]
62-63	\$003E-\$003F	144-145		DATA STATEMENT POINTER LO; HI [READ POINTER]
64-65	\$0040-\$0041	146-147	\$0092-\$0093	ETC) I DATA STMT PTR
66-67	\$0042-\$0043	148-149		CURRENT VARIABLE NAME [CURRENT VARIABLE

				SYMBOLS]
	\$0044-\$0045	150-151	\$0096-\$0097	POINTER TO VARIABLE IN MEMORY LO; HI [CURRENT
68–69	\$0044-40045	150-151		WARRIE START ADRI
70-71	\$0046-\$0047	152-153	\$0098-\$0099	POINTER TO VARIABLE REFERRED TO IN CURRENT
10-11	φυστο-φοστή	.555		FOR-NEXT
72-73	\$0048	154-155	\$009A	POINTER TO CURRENT OPERATOR IN TABLE LO; HI
73				.[154 Y SAVE REGISTER/NEW OPERATOR SAVE]
74.	\$004A	156	\$009C	SPECIAL MASK FOR CURRENT OPERATOR [CMPR
1				SYMBL ACMLTR <1=2>4]
75-76	\$004B-\$004C	157-158	\$009D-\$00A1	FUNCTION DEFINITION POINTER LO; HI [NUMBER
	•			WORK AREA FOR SQR] POINTER TO A STRING DESCRIPTION LO; HI [NMBR
77-78	\$004D-\$0050	159-160	\$009D-\$00A1	WRK AREA 157-161]
				CMBTVG
79.	\$004D-0050	161	\$009D-\$00A1	CONSTANT USED BY GARBAGE COLLECT ROUTINE
80.	\$004D <b>-</b> \$0050	162	\$00A2	[3 OR 7 FOR GRBG CLT]
		_	1 40015	THE THEORY OF THE THOUSENESS IN THE TOTAL PROPERTY OF THE TOTAL PR
81.	<b>\$</b> 0051 <b>-</b> \$0053	163	\$00A3-\$00A5	VECTOR FOR FUNCTIONS]
			40045	TARAMOTI I O. UT
82-83	\$0051-\$0053	164-165	\$00A3-\$00A5	FLOATING ACCUMULATOR #3 [NUMERIC STORE AREA]
84-89	\$0054-\$0058	166-171		
90-91	\$0059-\$005D	172-173	\$00AB-\$00AF	
				STORE AREA] BLOCK TRANSFER POINTER #2 LO; HI [NUMERIC
92-93	\$0059 <b>-</b> \$005D	174-175	\$00AB-\$00AF	
			Large Apare	STORE AREA] FLOATING ACCUMULATOR #1 (USER FUNCTIIION
94-99	\$005E-\$0063	178-181	\$00B0 <b>-</b> \$00B5	EVALUATED HERE)
				EVALUATED DEREY
95 • • • •		• • • • • • • • •	••••••	[PRIMARY ACCUMLATR E,M,M,M,M,S][MSB PARAMETERS 181-FLPT SIGN]
				DUPLICATE COPY OF MANTISSA OF FAC #1 [TAYLOR
100	\$0064	182	\$00B6	DUPLICATE COPI OF MANIISSA OF THE #1 LIMITED
				SERIES CONST CNTR] COUNTER - NUMBER OF BITS TO SHIFT TO
101	\$0065	183	\$00B7	COUNTER - NUMBER OF BILS TO SHIFT TO
				NORMALIZE FAC #1 [SEE 103]
102-107	\$0066-\$006B	184-189	\$00B8-\$00BD	FLOATING ACCUMULATOR #2 [SECONDRY ACUMULTR
103			• • • • • • • • • • • •	[101 IS ACCUMULATOR HIGH ORDER PROPOGATION
-				

108 109	\$006 C \$006 D	190 191	\$00BE \$00BF	WORD] OVERFLOW BYTE FOR FLOATING ARGUMENT [SIGN COMPARSN PRIM/SCND] DUPLICATE COPY MANTISSA SIGN [LOW ORDER ROUNDING BYTE-PRM ACML]
110-111	\$006E-\$006F		\$00C0=\$00C1	POINTER TO ASCII REP OF FAC IN CONVERSION ROUTINE LO; HI .[CASSETTE BUFFER LENGTH/TAYLOR CONSTANT
111 112-117 118 119-120 121-140	\$0070-0087 \$0070-\$0087 \$0070-\$0087 \$0088-\$008C	194-199 200 201-202 203-223	\$00C2-\$00D9 \$00C2-\$00D9 \$00C2-\$00D9	POINTER] CHARGET RAM CODE GETS NEXT CHARACTER FROM BASIC TEXT CHRGET RAM CODE TEGETS CURRENT CHARACTERS POINTER TO SOURCE TEXT LO; HI NEXT RANDOM NUMBER IN STORAGE / OR

136-140 141-143	\$0088-008C \$008D-\$008F	512-514	\$0200-\$0202	NEXT RANDOM IN STORAGE 24 HOUR CLOCK IN 1/60 SEC [CLOCK THAT INCREMENTS 60 PER SEC]
144-145	\$0090-\$0091	537-538	\$0219 <b>-</b> \$021A	IRQ RAM VECTOR LO; HI [BREAK INTERRUPT VECTOR]
146-147	\$0092-0093	539-540	\$021B-\$021C	BRK INSTRUCTION RAM VECTOR LO; HI [BREAK INTERRUPT VECTOR]
148 150 151	\$0094 <b>-</b> \$0095 \$0096 \$0097	524 515	\$020C \$0203	NMI RAM VECTOR  I/O OPERATION STATUS BYTE [STATUS (ST)]  LAST KEY INDEX [WHICH KEY DEPRSD/255=NO KEY]  [MATRIX ROW COLUMN]
152	\$0098	516	\$0204	SHIFT FLAG (0=NO SHIFT/1=SHIFT)[SHIFT KEY 1
153-154	\$0099-\$009A	517-518	\$0205-\$0206	CORRECTION FACTOR FOR CLOCK LSB; MSB [CLOCK INCREMENTS 30/SEC]
155.	\$009B	521	\$0209	DUPLICATE OF 59410(NEW?)BOTTOM ROW KEYS [KEYSWITCH PIA FLAGS]
157	\$009D	523	\$020B	FLAG <> MEANS VERIFY NOT LOAD INTO MEMORY [LOAD=0*VERIFY=1]
158	\$009E	525	\$020D	INDEX INTO KEYSTROKE BUFFER [# OF CHARACTERS KYSTRK BUFFER]

159	\$009F	526	\$020E	FLAG TO INDICATE REVERSE FIELD ON
160-166	\$00A0-\$00A6			UNUSED
167	\$00A7	• • • • •	••••	CURSOR ON FLAG COUNT OF JIFFIES TO BLINK CURSOR [CURSOR
168	\$00A8	549	\$0225	TIMING CNTDN][POKE=1]
			1	SCREEN VALUE OF CHARACTER UNDER CURSOR
169	\$00A9 \$00AA	550	\$0226	CHAR SAVED DURING BLNK/CRSR ON/OFF FLG [CURSR
170	\$00AA	551	\$0227	BLNK FLG/POKE=0]
				UNUSED
171-173	\$00AB-\$00AB	••••	****	POINTER INTO LOGICAL FILE TABLE [NUMBER OF
174	\$00AE	610	\$0262	OPEN FILES]
			40062	DEFAULT INPUT INTO DEVICE # [NORMALLY=0]
175	\$00AF	612	\$026 A	DEFAULT OUTPUT DEVICE # [OUTPUT TO CMD
176	\$00B0	012	\$U2U A	DEVICE NORMALLY=3]
	10004	643	\$0265	TAPE VERTICAL PARITY/COMPUTATION OF PARITY
177	\$00B1	013	\$UZUS	ON CASSETTE WRITE
	+++			IMUSED
178-185	\$00B2-\$00B9			GENERAL PURPOSE AND ADDRESS DIRECT LO; HI(ALSO
180	\$00B4	229-233		T OCA TRY 201_20は)
.04	ACORE	616	\$0268	
181	\$00B5			· — —
404	\$00B8	621	\$026 D	[COUNT OF REDUNDANT TAPE BLOCKS]
184 186	\$00BA	624	\$0270	DING ON THE HEIDER COURTS
• • •	<b>*</b>			SYNC ON CASSETTE WRITE
187_188	\$00BB-\$00BC	625-626	\$0271-\$0272	POINTER TO ACTIVE CASSETTE/OR
188				. INDEX NEXT CHARACTER IN OUT IME DOLL " ,
100				#2 187 FOR #1/188 - #2
189	\$00BD	627	\$0273	COUNTDOWN SYNCHRONISATION - CASSETTE READ
10)	<b>400</b>	•		READ[LEAD CNTR/PASS 1/2]
190	\$00BE	628	\$0274	FLAG TO INDICATE BIT/BYTE TAPE ERROR[WRITE
.,,,				NEW BYTE]
191	\$00BF	629	<b>\$</b> 02 <b>7</b> 5	FLAG TO INDICATE TAPE ROUTINE READING SHORTS
	•			[WRITE START BIT]
192-193	\$00C0-\$00C1	630–631	\$00C0-\$00C1	INDEX TO ADDRESSES TO CORRECT ON TAPE READ
193		• • • • • • • •	• • • • • • • • • • • • • • • • • • • •	[192 FOR PASS 1 ERROR LOG POINTR/193 FOR PASS 2 ERR LOG PNTR]
		600	4007 P	FLAG-CASSETTE READ-TELLS CURRENT FNCTN-
194	\$00C2	632	\$U278	CNTDWN, READ
		622	<b>#</b> 027.0	COUNT OF SECONDS OF SHORTS TO WRITE BEFORE
195	\$00C3	633	\$UZ1 7	DATA [CHECKSUM]
				Nutre Farmand

					TOTAL CORPUS POSTSTON
19	96-197	\$00C4-\$00C5	224-225	\$00E0-\$00E1	POINTER TO CURSOR POSITION [SCREEN POSITION ON LINE]
19	98	\$00C6	226	\$00E2	COLUMN POSITION OF CURSOR [POSITION OF
19	99-200	\$00C7-\$00C8	227-228	\$00E3-\$00E4	LOAD START ADDRESS LO; HI [UTILITY POINTER] .[TAPE BUFFER, SCROLLING][INVERSE VIDEO CURSOR=1]
2	00	• • • • • • • • • • • • •	• • • • • • • •		CURSOR=1]
					PRINT LOAD END ADDRESS LO; HI (INCLUDING LOCATION 180 LOND OF CURPENT PROGRAM/TAPE END ADDRESS]
2	02			******************************	FLAG FOR QUOTE MODE ON/OFF [DIRECT/PROGRAMMED
2	05	\$00CD	234	ŞUUEA	FLAG FOR QUOTE MODE ON/OFF [DIRECT/PROGRAMMED CURSOR*0=DIRECT]
					IINIISED
		\$00CE-\$00D0	238	\$00EE	CURRENT FILE NAME LENGTH [NUMBER OF CHAR-
2	209	\$00D1	230	φυσμ	ACTERS IN FILE NAME
_		\$00D2	530	\$00EF	CURRENT RILE LOGICAL ADDRESS [GPIB FILE #]
_	210		240	\$00F0	CURRENT PRIMARY ADDRESS FILE [FILE COMMAND
2	211	\$00D3	240	40020	(FROM OPEN) I GPTR CMND]
	.40 043	\$00D4-\$00D5	211-242	\$00F1-\$00F2	CURRENT SECONDARY ADDRESS [212 DEVC #][213
2	212-213	\$0004-4000J	2-11-2-12	40000	MAY TINE LITH 40/80]
,	04 II 04 E	\$00D6_\$00D7	243-244	\$00F3-\$00F4	START OF CURRENT TAPE BUFFER POINTER LO; HI
	214-215 216	\$00D0-\$00D1	245	\$00F5	CURRENT SCREEN LINE # [LINE WHERE CURSOR
•	210	φυυσυ	5	·	LIVES]
	017	\$00D9	246	<b>\$</b> 00 <b>F</b> 6	DATA TEMPORARY FOR I/O [LAST KEY HIT(ASCII)*
	217				DUDDED CUPCKSIIM!
	218_210	\$00DA-\$00DB	249-250	\$00F9-\$00FA	POINTER TO CURRENT FILE NAME LO; HI [FILE NAME
•	210-219	Ψ002 Ψ000-			LOTHIDKI
	220-221	\$00DC-\$00DD	••••	••••	UNUSED
	222	\$00DE	• • • • •		CASSETTE READ BLOCK COUNT
	223	\$00DF			UNUSED ADDRESSES OF VIDEO DISPLAY
	227-278 552	\$00E0-\$00F8	553-577	\$0229-\$0241	TABLE OF LIST STATE
		,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,			LINES (25)
	225				[SCREEN LINE WRAP TABLE]  INTERRUPT DRIVER FLAG FOR CASSETTE # 1
	249-250	\$00F9-\$00FA	519-520	\$0207-\$0208	NTERRUPT DRIVER FLAG FOR CALCULATION OF THE CALC
		•			SWITCHES; # 2 SWITCHES

250				[249 FOR CASSETTE #1 ON][250 FOR CASSETTE
251-252	\$00FB-\$00FC	247-248	\$00F7 <b>-</b> \$00F8	POINTER TO START LOC FOR O.S. LO; HI [TAPE START ADDRESS*TAPE PNT] [POINTER TO PROGRAM DURING VERIFY, LOAD]
512-591	\$0020~\$0250	10-69	\$00¥0+\$0003	BASIC INPUT BUFFER (80 BYTES)[NUMBER OF ARRAY SUBSCRIPTS] .512-513 IS THE PROGRAM COUNTER .514 IS PROCESSOR STATUS
				.514 IS PROCESSOR STATUS .515 IS ACCUMULATOR .516 IS X INDEX
516	• • • • • • • • • • • • • • • • • • • •	• • • • • • • • •		.517 IS Y INDEX
518	• • • • • • • • • • • •	• • • • • • • • • •	•••••	510-520 IS USER MODIFIABLE IRQ
593-602	\$0251-\$025A	578-587	\$0242-\$0240	OPEN FILES]
603 <b>-</b> 612	\$025B-\$0264	588-597	\$024C-\$0255	WTLEST
613-622	\$0265-\$026E			TABLE OF SECONDARY ADDRESSES [COMMAND/ SECONDARY ADRS OPEN FIL]
623 <b>-</b> 632 634 <b>-</b> 825	\$026F-\$0278 \$027A-\$0339		\$020F-\$0218	INTERRUPT DRIVEN KEYSTROKE BUFFER BUFFER FOR CASSETTE #1 (192 BYTES)
826-1017	\$033A-\$03F9	826-1017	\$033A-\$03F9	BUFFER FOR CASSETTE #2 (192 BYTES)

# **Bits & Bytes**

The Independent PET Users' Group (South) has been re-named, and is now known as SUPA (Southern Users of PETs Association).

Their former position as a regional Group for IPUG is now terminated.

Subscription rate for 12 months is now 5.00. Applicants should contact the Membership Secretary:

Howard Pilgrim 42 Compton Road Brighton Sussex BN1 5AN

PET SPEAKS

Petsoft have released a 10 'Talking Claculator' program which generates synthetic speech via an inexpensive soundbox connected to the user port of the Commodore PET microcomputer.

Once loaded, the program causes the name of each numeric or function key to be generated as synthetic speeck, followed by the result of the calculation. The representation of a calculator on screen allows the calculation to be tracked visually as well.

As each key is depressed, the computer responds with the words: "Six...divided...by...four...equals...one ...point...five".

The 'Talking Calculator' is available, price 10 + VAT from PET dealers, or by mail order direct from ACT Petsoft, 66-68 Hagley Road, Edgbaston, Birmingham, B16 8PF. A User Port Speech and Music Generator with volume control and connectors is also on sale priced at 27 + VAT

## SPACE INVADERS ZAP PET

I, for one, have worn the 'A' key out on my PET. Here is an ideal solution by G. Luxford .....

"I have found the SPACE INVADER program to be a knock-out, but the key for beam firing, "A" is coming in for severe pounding, particularly when other over enthusiastic hands get onto the keyboard.

With the new ROM version a temporary solution is to shift the commands onto different keys. This can be achieved by POKE1409,6 after loading but prior to running the program, to shift commands to Z, 1 and 3. This location can alternatively be POKEd with any value from 0 to 9, except 4 (present values) to select

other options for the keyboard. Another option is to POKE1938 with 2, 4, 8 or 16 to shift the beam fixing key along the key row.

A better solution is to shift the control to the user port input. This can be achieved by POKE1414,79 and POKE1417,79. Control is then by switch closers to the ground line, pin N of PAO on pin C to fire beam, PA7 on pin L to move the laser base right and PA6 on pin K to move the laser base left. You can now use large hefty buttons or a joy stick control with complete immunity to keyboard damage by over-excited saucer shooters.

You may SAVE the program either by BASIC without a name or by TIM monitor, from \$0400 to \$2000.

The program is also being modified to give the option of any alpha key to fire the beam, any numeric key to shift the laser base and the option of control by the user port. This requires appreciably more patching and is not yet fully debugged.

When completed I will send details with a revised program to CPUCN.

I regret not being of direct help to old ROM users, having recently become a new ROMer, but can only suggest they try the recommended program mods and see what happens. There seems a good chance this will work."

The result of the PET Show Prize Draw.

The draw was made by Kit Spencer, in the presence of students on a BASIC for Beginners course at the Skyway Hotel on 17 June.

The winner of the 95 software prize is:-

E Ramsden The Country House 123 Greenland Road Hemel Hempstead HK1 1RT

1= poen = C 3 = blow = 4 5 = \$pood = L N Ha Sound = wil = M